



RDECOM



TECHNOLOGY DRIVEN. WARFIGHTER FOCUSED.

BRL-CAD Overview

June 2009

Mr. Christopher "Sean" Morrison

morrison@arl.army.mil

410-278-6678



Main Goals



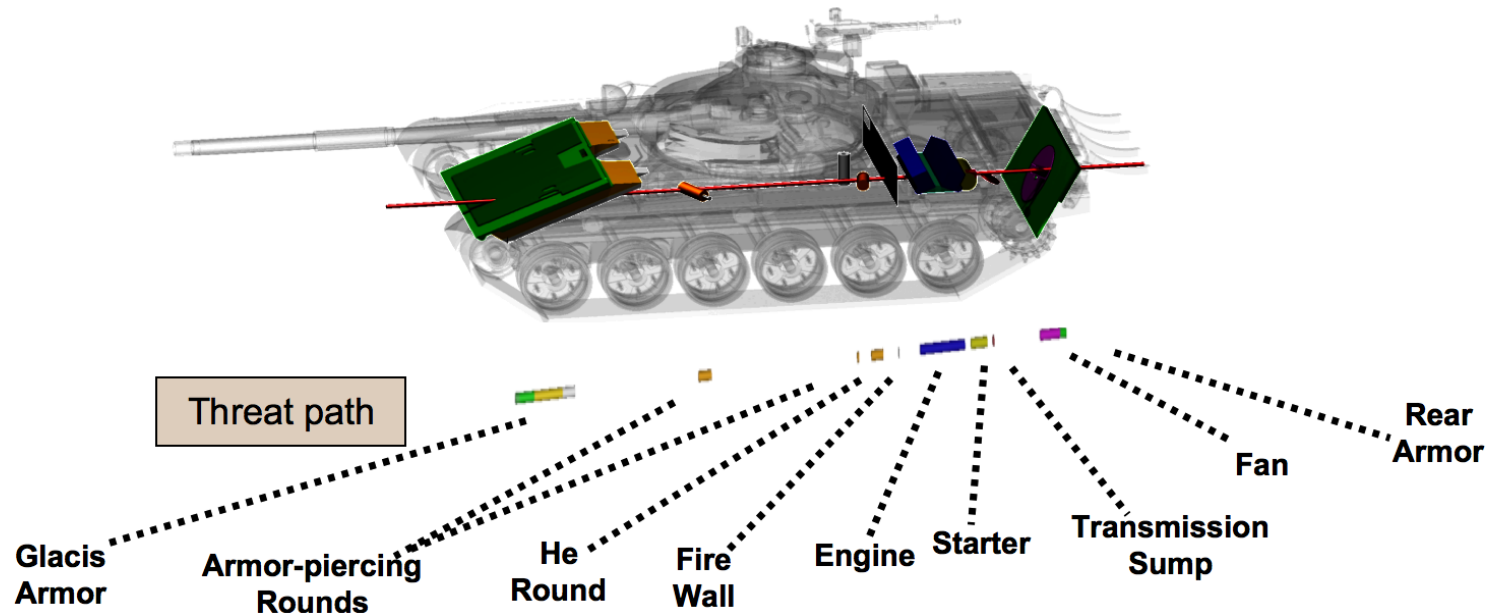
***BRL-CAD Tools & Techniques
for Visualization***

***BRL-CAD Tools & Techniques
for Geometry Analysis***

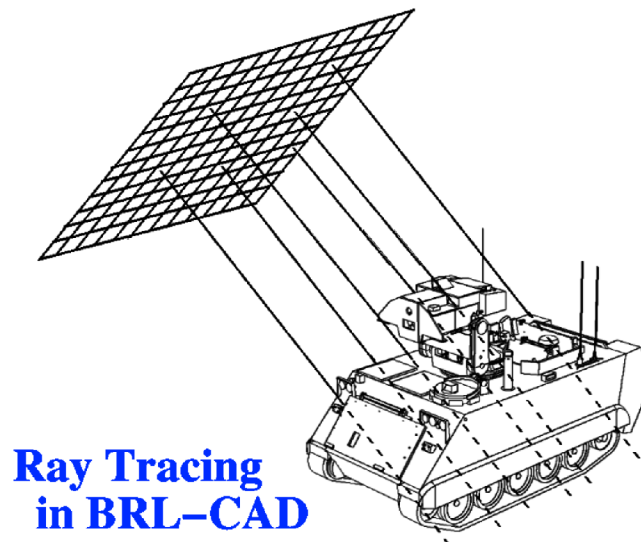
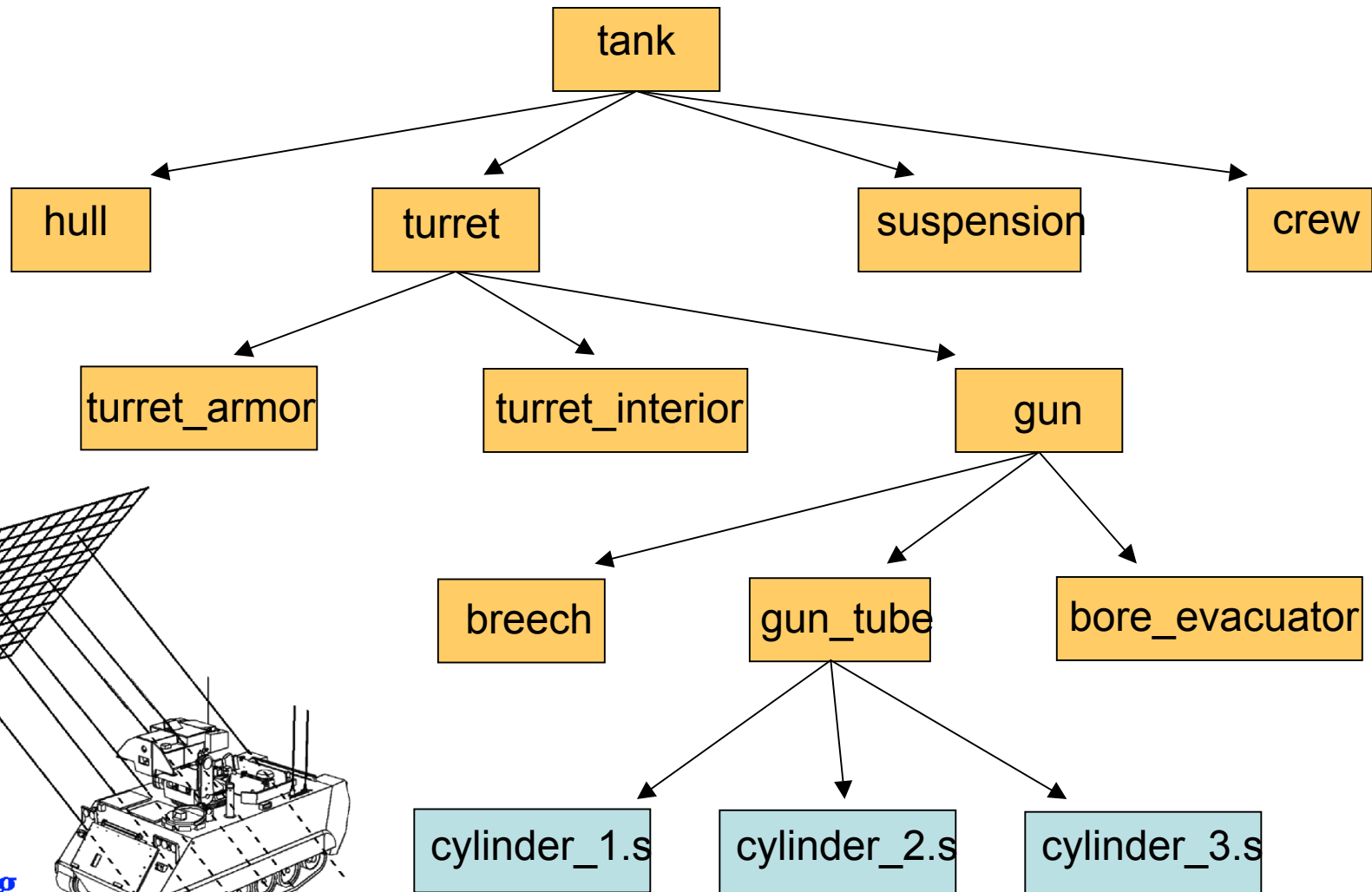
***Boundary Representation & Conversion Support
(BREP/NURBS & STEP)***

BRL-CAD Geometry Service & Parts Library

- BRL-CAD* is a powerful open source solid modeling system that includes interactive geometry editing, ray tracing for rendering & geometric analyses, a robust geometric representation, image & signal-processing tools, and more than 25 years of development history.
- Development of BRL-CAD directly supports ARL's strategic focus by providing tools, techniques, and methodology for performing vulnerability and lethality analyses. It is not only an asset within ARL, but to organizations and individuals around the world.



* BRL-CAD is correctly pronounced as "be are el cad"



- More than one million lines of code
- More than 400 binary applications
- More than a dozen libraries

1998 Technical Advisory Board, National Research Council

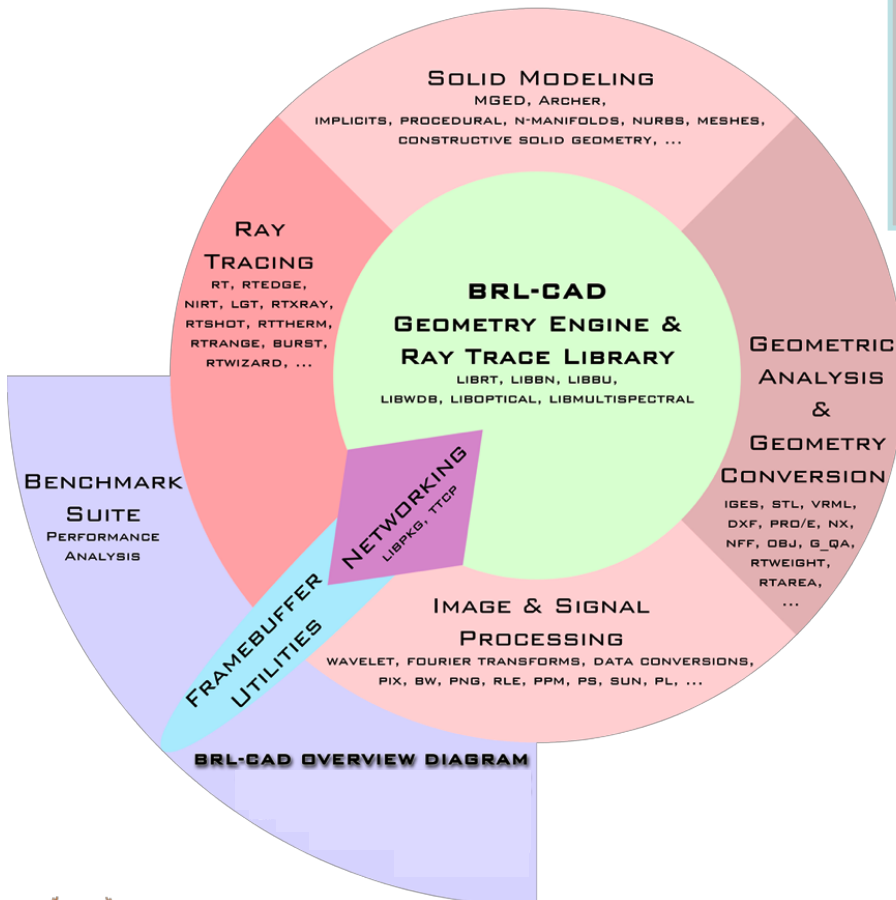
“an effective constructive solid modeling capability with highly efficient ray tracing”

...

“a computer-aided engineering (CAE) system uniquely suited to survivability and lethality applications”

...

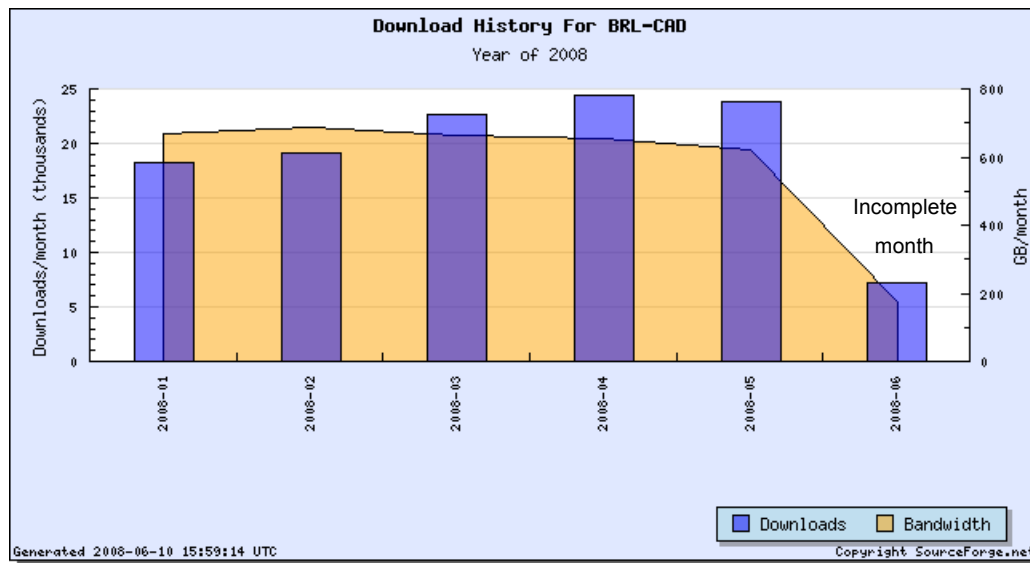
“a platform for a ‘virtual test environment’ that could provide a powerful, cost-effective capability for survivability and lethality evaluation”



- Extensively cross-platform Windows, Mac, Linux, UNIX, ... *from desktops to supercomputers*
- Became Open Source software in 2004
Open code, Open access, Open standards ... It's free!
- BRL-CAD is the first & only Open Source solid modeling system in production use under OSI*-approved license terms



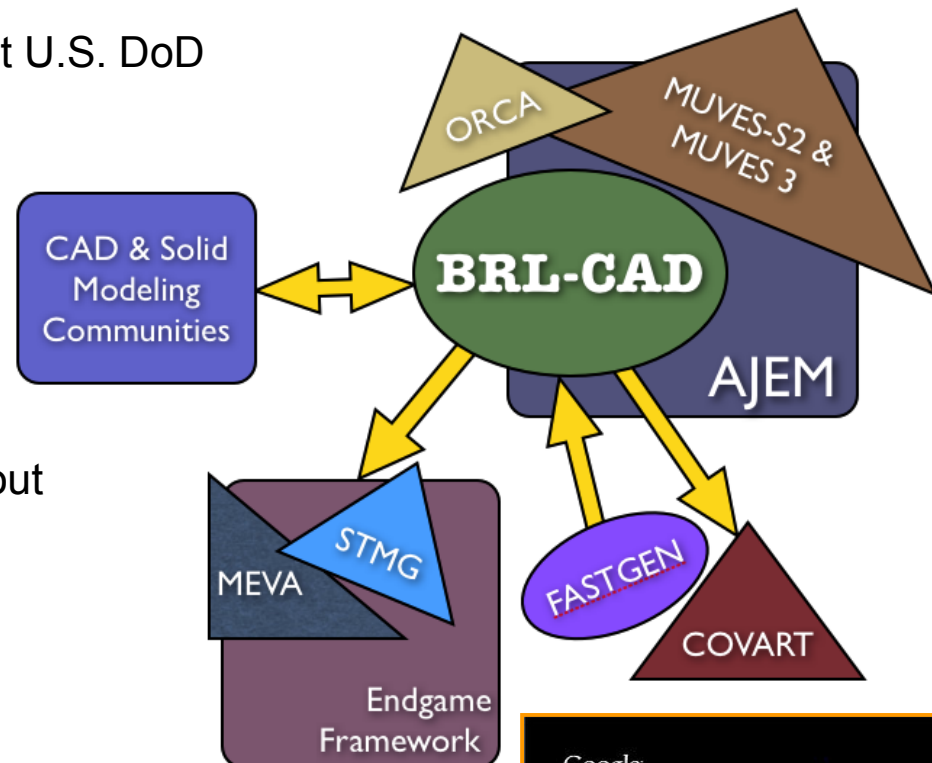
BRL-CAD Open Source Statistics



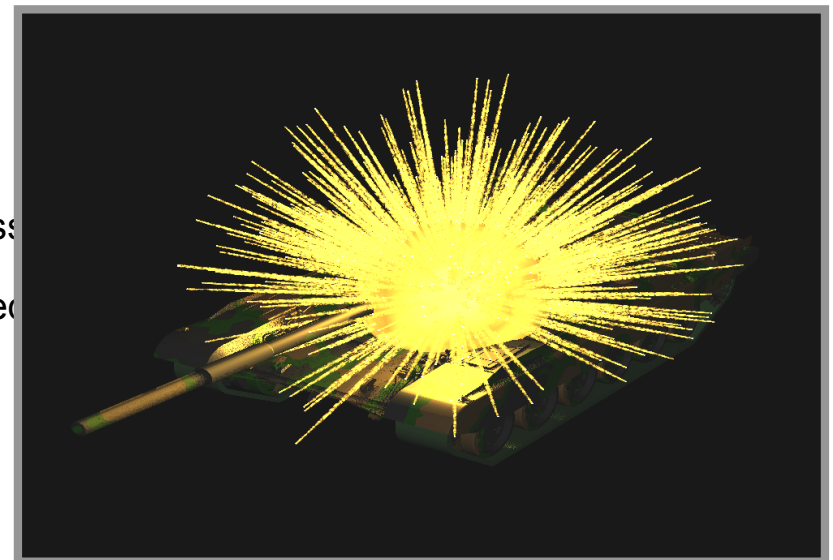
***“the world’s oldest
source code
repository”***
– August 2007,
Robin Luckey, Ohloh Inc.

- More than **200,000** downloads and **2,000,000** website hits per year (as of 2008)
- Activity (both interest and development) is increasing year over year
- Presently receiving about **three-to-five staff-years** of contributed effort from the Open Source community including source code enhancements, bug fixes, documentation, website development, and more
- Received roughly an additional staff-year of effort in 2008 and 2009 by being accepted into the **Google Summer of Code**

- SLAD V/L analysts and target describers
- MUVES and AJEM users throughout U.S. DoD
 - *Army, Air Force, Navy*
- International collaborations: Senior National Representative V/L Assessment Methodology (VLAM) working group
 - *United Kingdom, Germany, Netherlands, ...*
- Extensive international ties throughout the Open Source communities, academia, and commercial industry
 - *University of Utah*
 - *University of North Carolina at Chapel Hill*
 - *Johns Hopkins University*
 - *Texas A&M University*
 - *... and much more ...*
- Google Summer of Code
 - *Exclusive Open Source opportunity*



- BRL-CAD is custom-tailored to engineering analysis work providing high-performance geometric representation and geometry evaluation.
 - There is no conversion involved which is crucial for ensuring robust, consistent, and correct analytic results. *Data conversions introduce errors.*
- BRL-CAD is integral to V/L analyses where ray tracing is used to represent material interactions and determine paths of material propagation.
 - This is a **niche** requirement not strongly supported by other CAD systems.
- Ray tracing support in BRL-CAD is specifically tailored to MUVES and AJEM which typically require shooting millions of rays (with millimeter accuracy) at highly detailed target descriptions.
 - BRL-CAD's ray-tracing **outperforms** commercial ray tracers per internal development comparisons made against Unigraphics/NX, Pro/ENGINEER, and other CAD systems.
- Hundreds of existing BRL-CAD target descriptions represent a major investment that has been made over more than two decades.
 - **Extensive** model repositories exist at ARL and AFRL of foreign and U.S. assets.
- BRL-CAD's ray tracing provides scalability, robustness and verifiable accuracy that can perpetually and independently be customized and extended as needed.
 - This allows the U.S. Government to not favor any particular CAD vendor, avoids expensive licensing, and protects ARL against corporate restructuring.
- **BRL-CAD is highly tuned to ARL's needs, more than any other CAD system.**



TECHNOLOGY DRIVEN. WARFIGHTER FOCUSED.



Main Goals



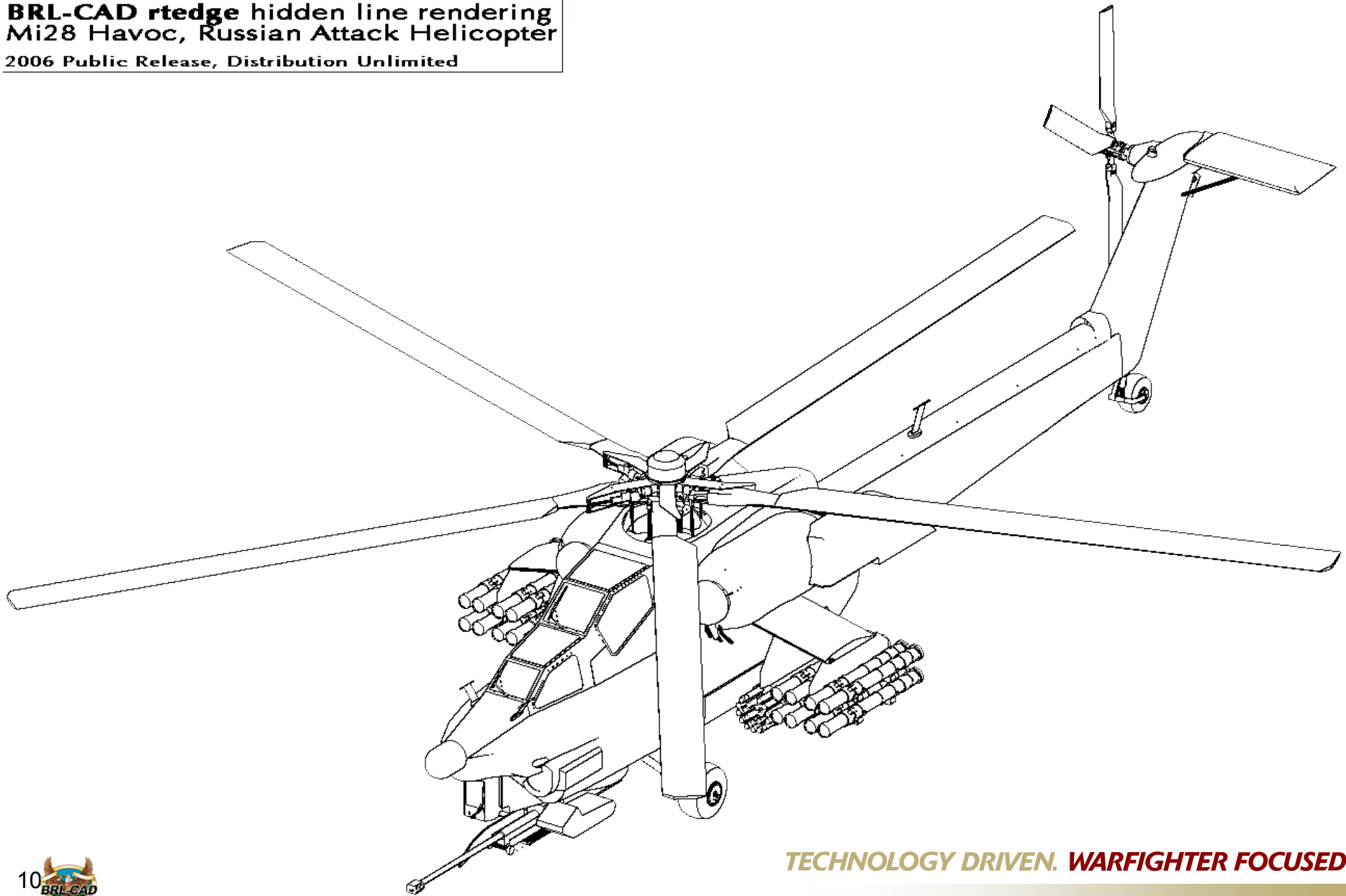
***BRL-CAD Tools & Techniques
for Visualization***

***BRL-CAD Tools & Techniques
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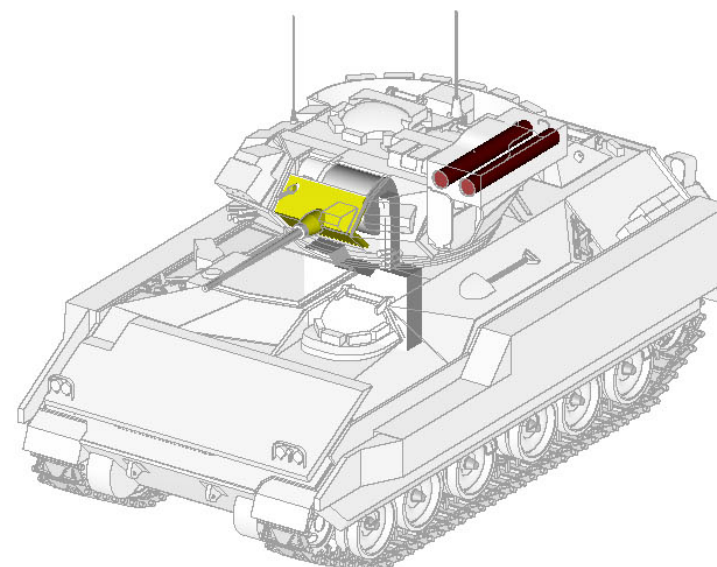
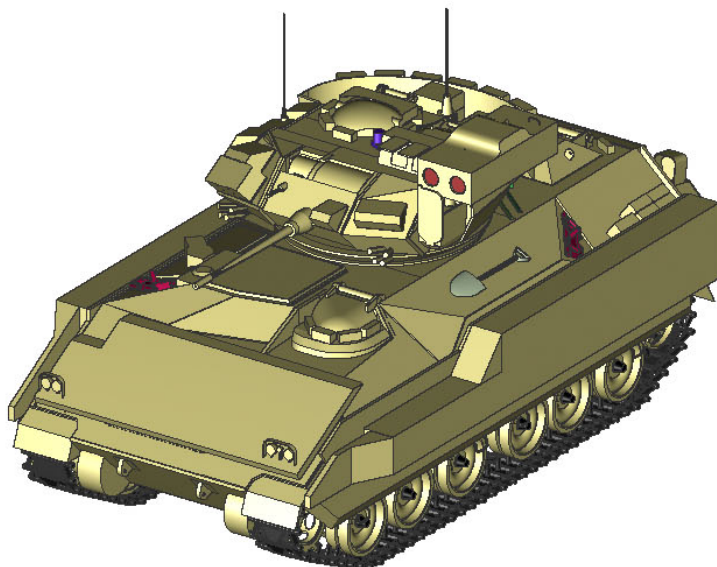
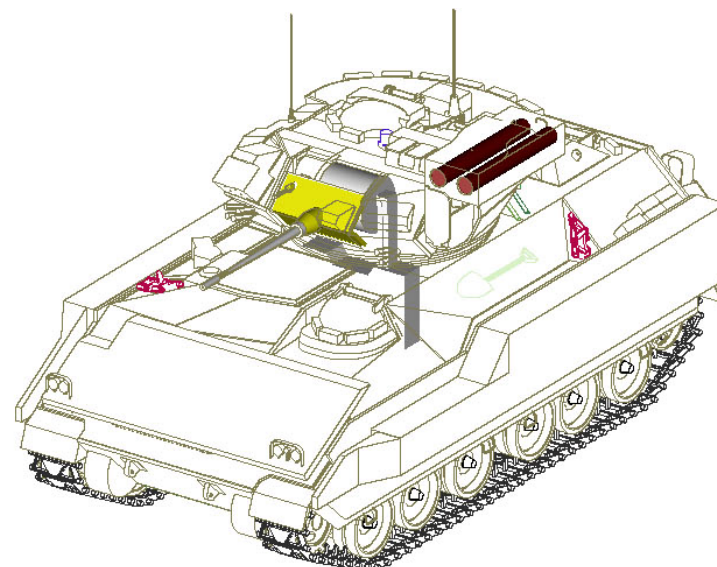
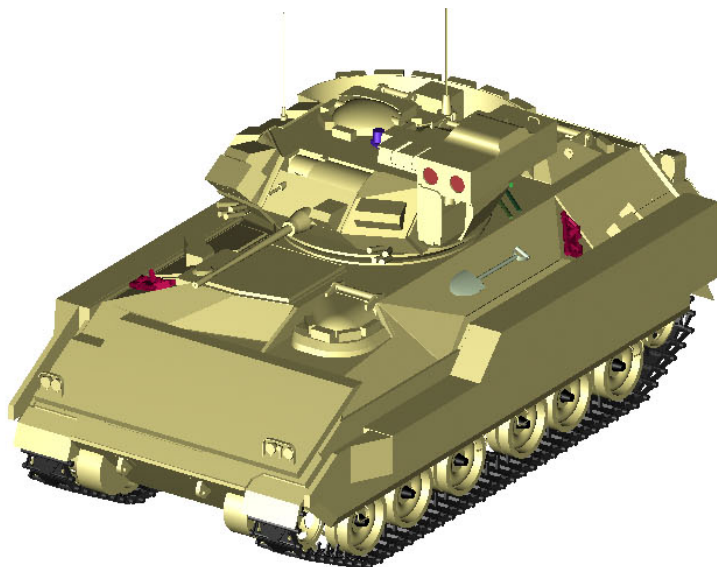
***Boundary Representation & Conversion Support
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BRL-CAD Geometry Service & Parts Library

BRL-CAD rtedge hidden line rendering
Mi28 Havoc, Russian Attack Helicopter
2006 Public Release, Distribution Unlimited



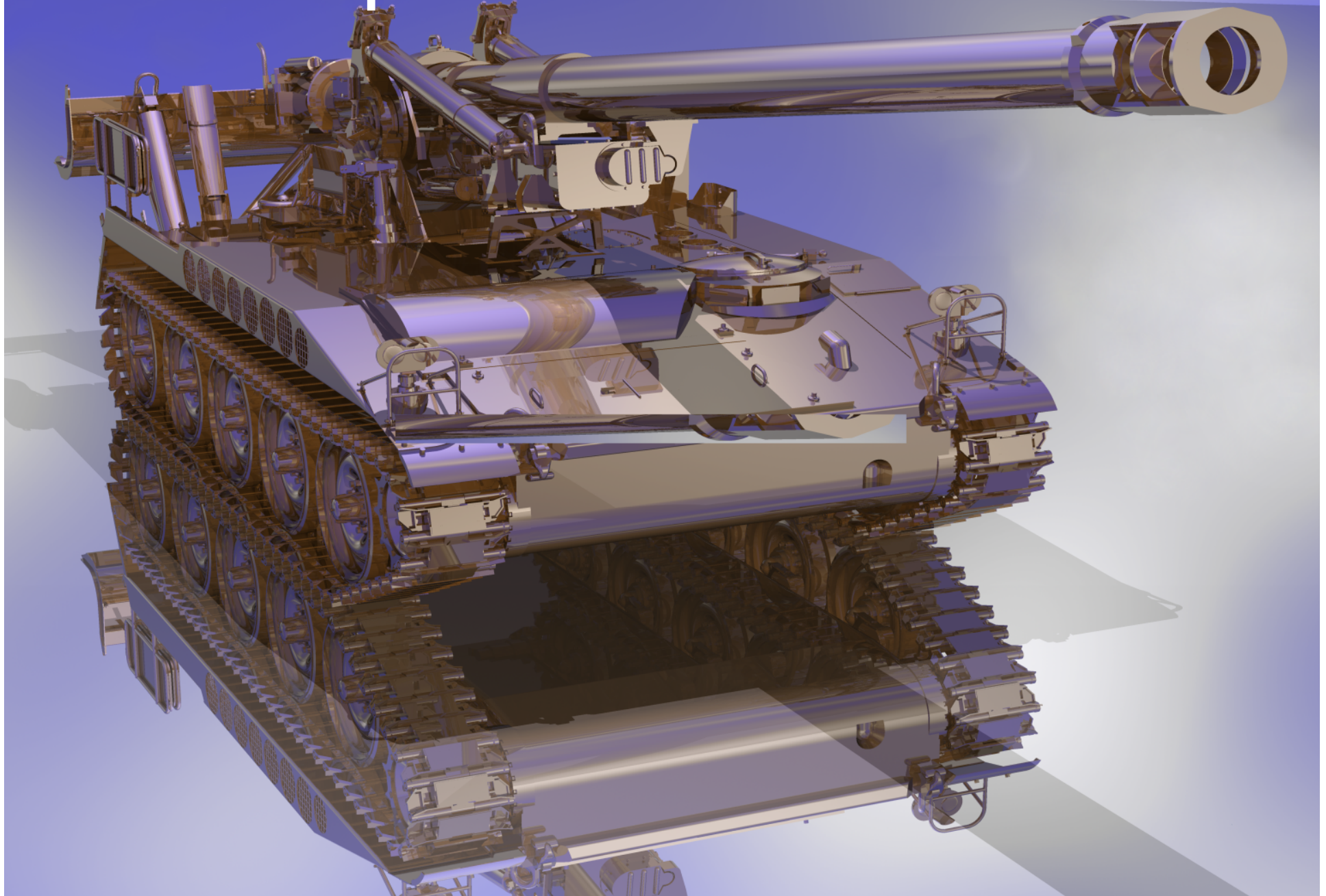
TECHNOLOGY DRIVEN. WARFIGHTER FOCUSED.



Example Aircraft: Fairchild A10



Example Ground: M110 Howitzer



Component Colorization

```
col writeToFile filename
mged> col loadDatabaseMappings
Loading database... [please wait] ...
...done
SHOT: cpu = 70 sec, elapsed = 167.181 sec
  parent: 70.0user 0.0sys 2:47real 41% Oi+0d 0
  children: 0.0user 0.0sys 2:47real 0% Oi+0d 0ma
Additional mem=0., #malloc=1065, #free=945, #rea
10929606 solid/ray intersections: 4626393 hits +
pruned 42.3%: 27744 model RPP, 18744539 dups sk
Frame 0: 855625 pixels in 70.00 sec =
Frame 0: 855625 rays in 70.00 sec =
Frame 0: 855625 rays in 70.00 sec =
Frame 0: 855625 rays in 167.18 sec =
```

Raytrace complete.

mged>

cent=(1121.986 707.398 1761.675) sz=3700.000 mm az
1.68 fps

Raytrace Control Panel (id_0)

Framebuffer Objects

Source .topid_0.ur

Destination .topid_0.ur

Size 925x925

Background Color 0 0 0

Raytrace

Abort

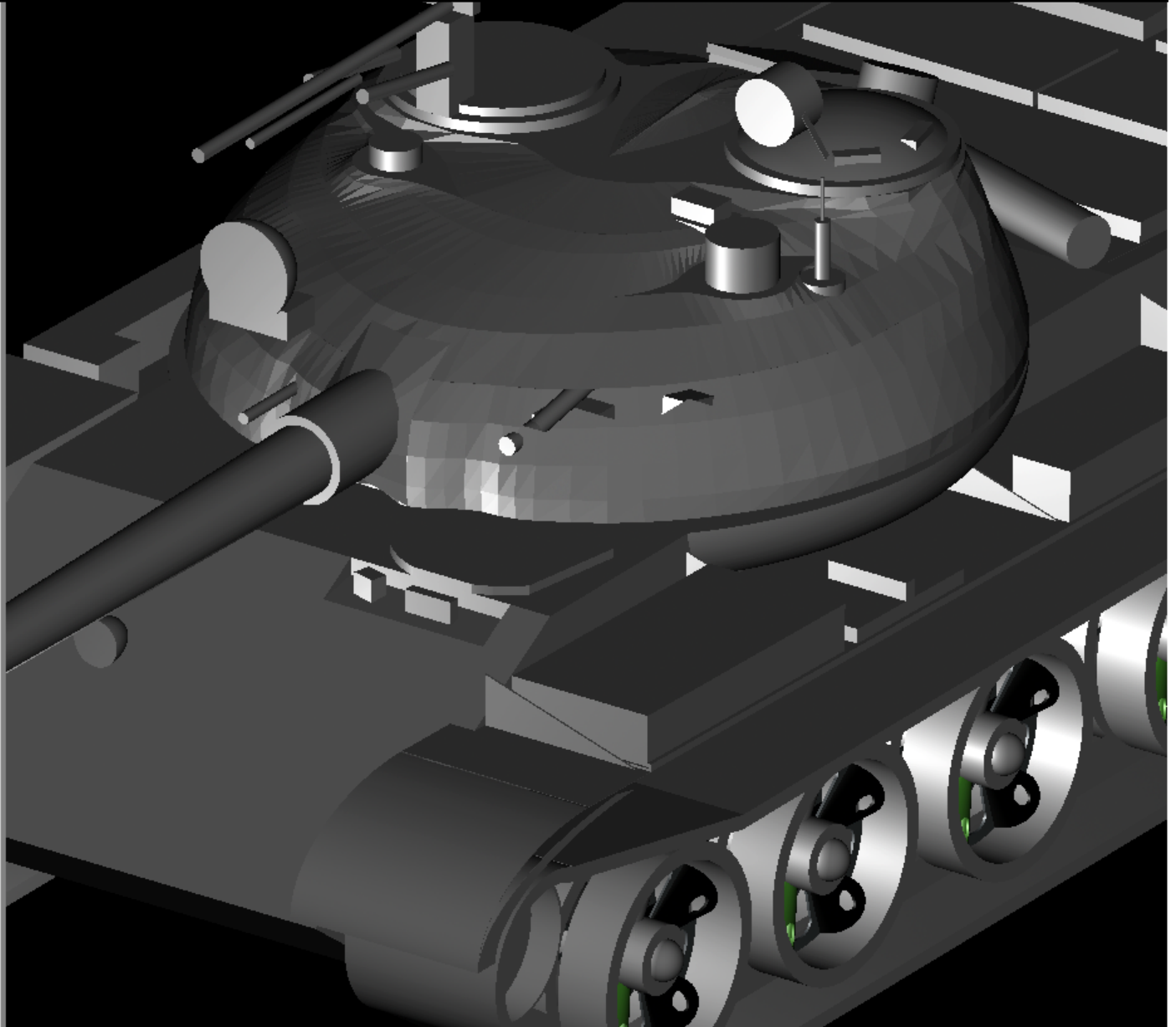
fbclear

Advanced Settings..

Dismiss

Reload Stop Reveal in F

GDC2001-Examples-20010323-1.dmg



Component Colorization

```
Lighting: Ambient = 40%  
Implicit light 0: (2434.22, -561.992, 777.001)  
Implicit light 0: invisible, no shadows, 1000
```

```
SHOT: cpu = 20.22 sec, elapsed = 31.0288 sec  
parent: 20.2user 0.0sys 0:31real 65% 0i+0d 0ma  
children: 0.0user 0.0sys 0:31real 0% 0i+0d 0ma  
Additional mem=0., #malloc=1004, #free=943, #rea  
2975926 solid/ray intersections: 1261626 hits +  
pruned 42.4%: 100832 model RPP, 2602902 dups sk  
Frame 0: 855625 pixels in 20.22 sec =  
Frame 0: 855625 rays in 20.22 sec =  
Frame 0: 855625 rays in 20.22 sec =  
Frame 0: 855625 rays in 31.03 sec =
```

Raytrace complete.

mged>

```
cent=(-415.201 -349.647 922.036) sz=3700.000 mm az=  
4.10 fps
```

```
bash2.04 sean@pcp01840101pcs ~/col  
total 16632
```

Raytrace Control Panel (id_0)

Framebuffer Objects

Source .topid_0.ur

Destination .topid_0.ur

Size 925x925

Background Color 0 0 0

Raytrace

Abort

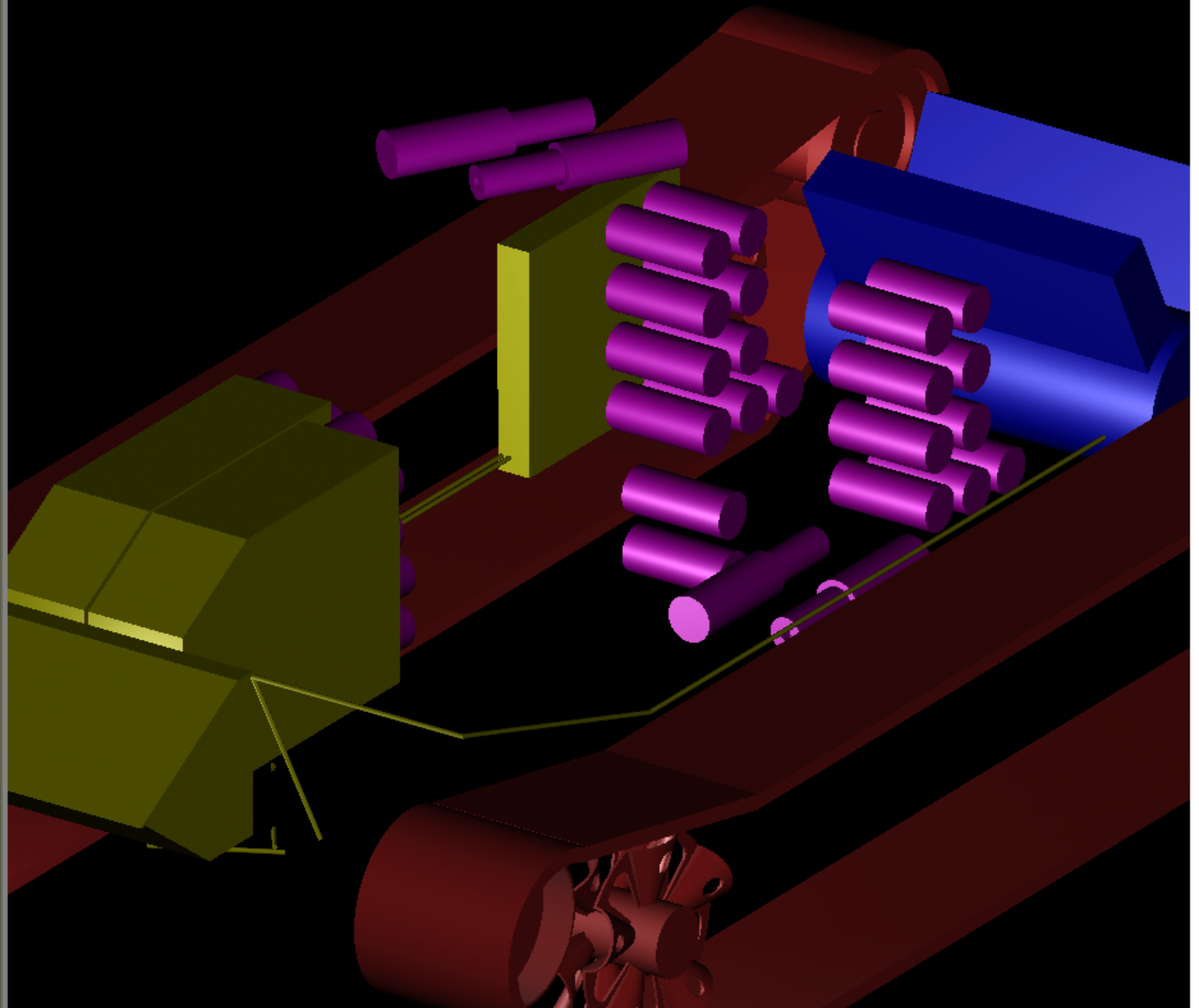
fbclear

Advanced Settings..

Dismiss

```
-rw-r----- 1 sean staff 603  
-rw-r----- 1 sean staff 366  
-rw-r----- 1 sean staff 246599  
-rwxr-xr-x 1 sean staff 329  
-rw-r----- 1 sean staff 424  
-rw-r----- 1 sean staff 488  
-rwxr-x--- 1 sean staff 233600  
-rwxr-x--- 1 sean staff 1633  
-rwxr-x--- 1 sean staff 4430  
bash2.04 sean@pcp01840101pcs ~/col
```

Reload Stop Reveal in F
GDC2001-Examples-20010323-1.dmg





Example Full Light Simulation



Stryker ICV w/ Slat Armor

11,542,992 Triangles

Rendered with ADRT/RISE

8 Trillion Rays



Main Goals



*BRL-CAD Tools & Techniques
for Visualizations*

***BRL-CAD Tools & Techniques
for Geometry Analysis***

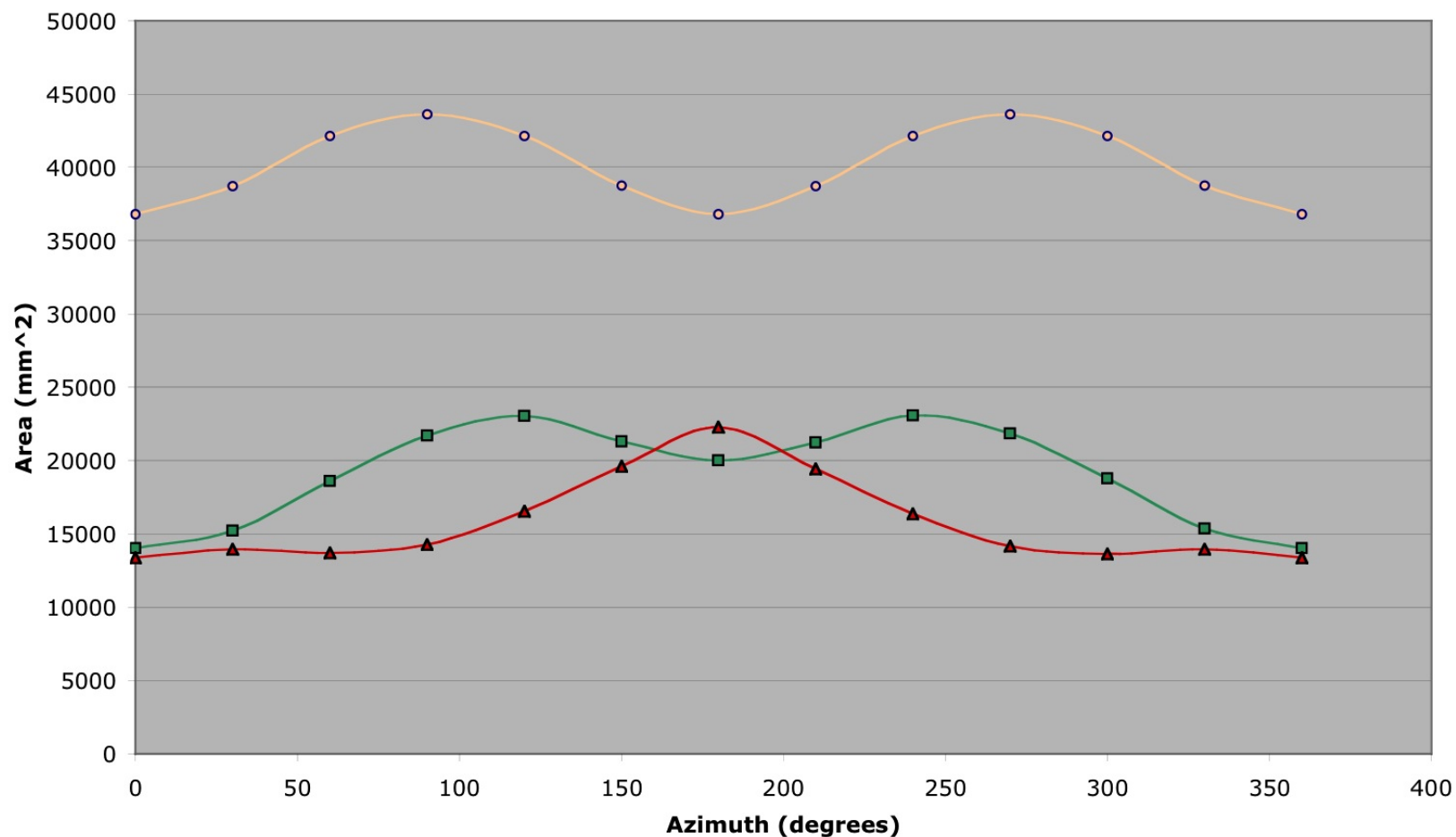
*Boundary Representation & Conversion Support
(BREP/NURBS & STEP)*

BRL-CAD Geometry Service & Parts Library

Presented Area, Weight/Mass,
Volume, Line-of-sight Equivalence,
Shape Factors, ...

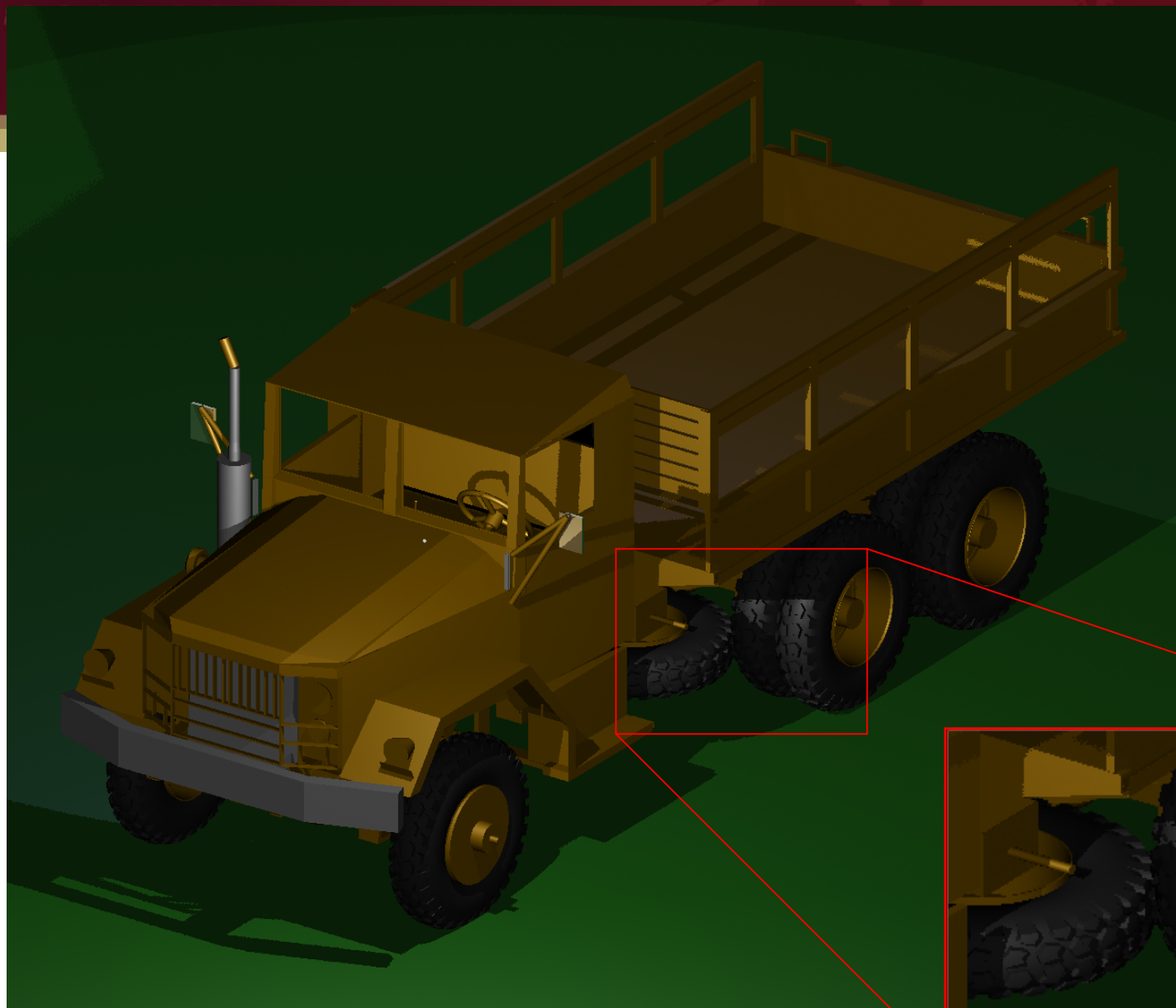


Helmet presented area coverage comparisons



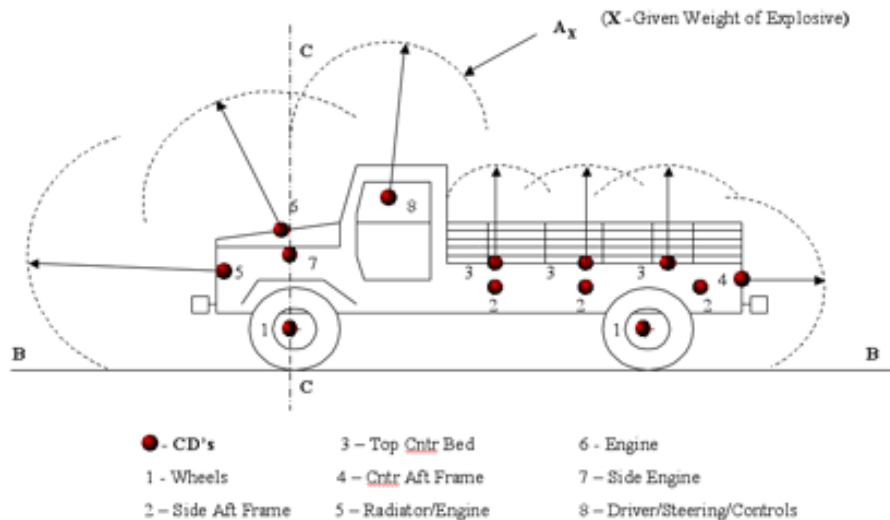


Automatic Detailed Tire Modeling



TECHNOLOGY DRIVEN. WARFIGHTER FOCUSED.

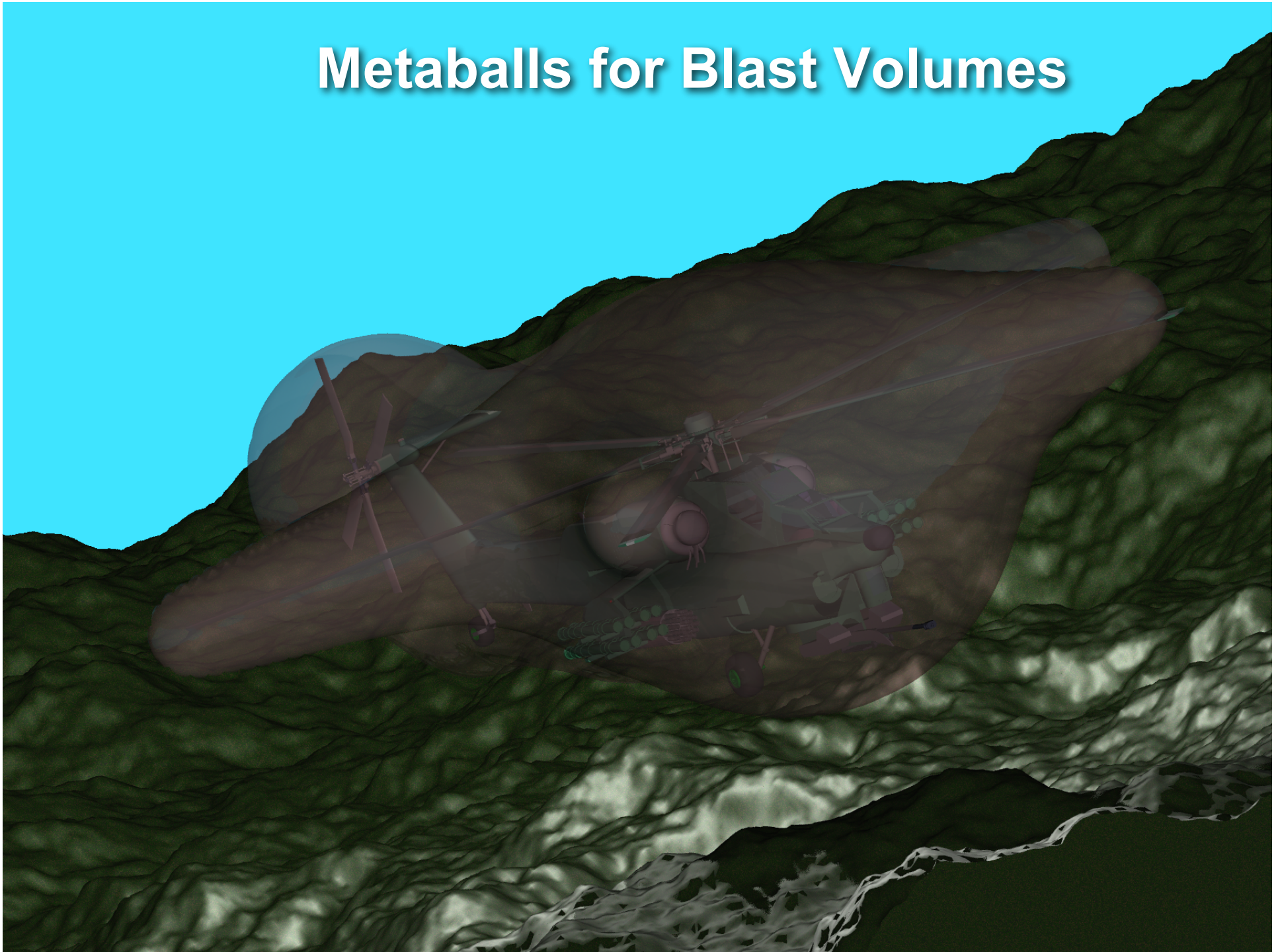
- The engineer traditionally:
 - Specifies a center of damage and lethal miss distance
 - Manually interpolates a curve in 2D
 - That 2D curves is then extrapolated into a 3D surface
- With metaballs, the 3D surface is automatically generated based on centers and lethal miss distances



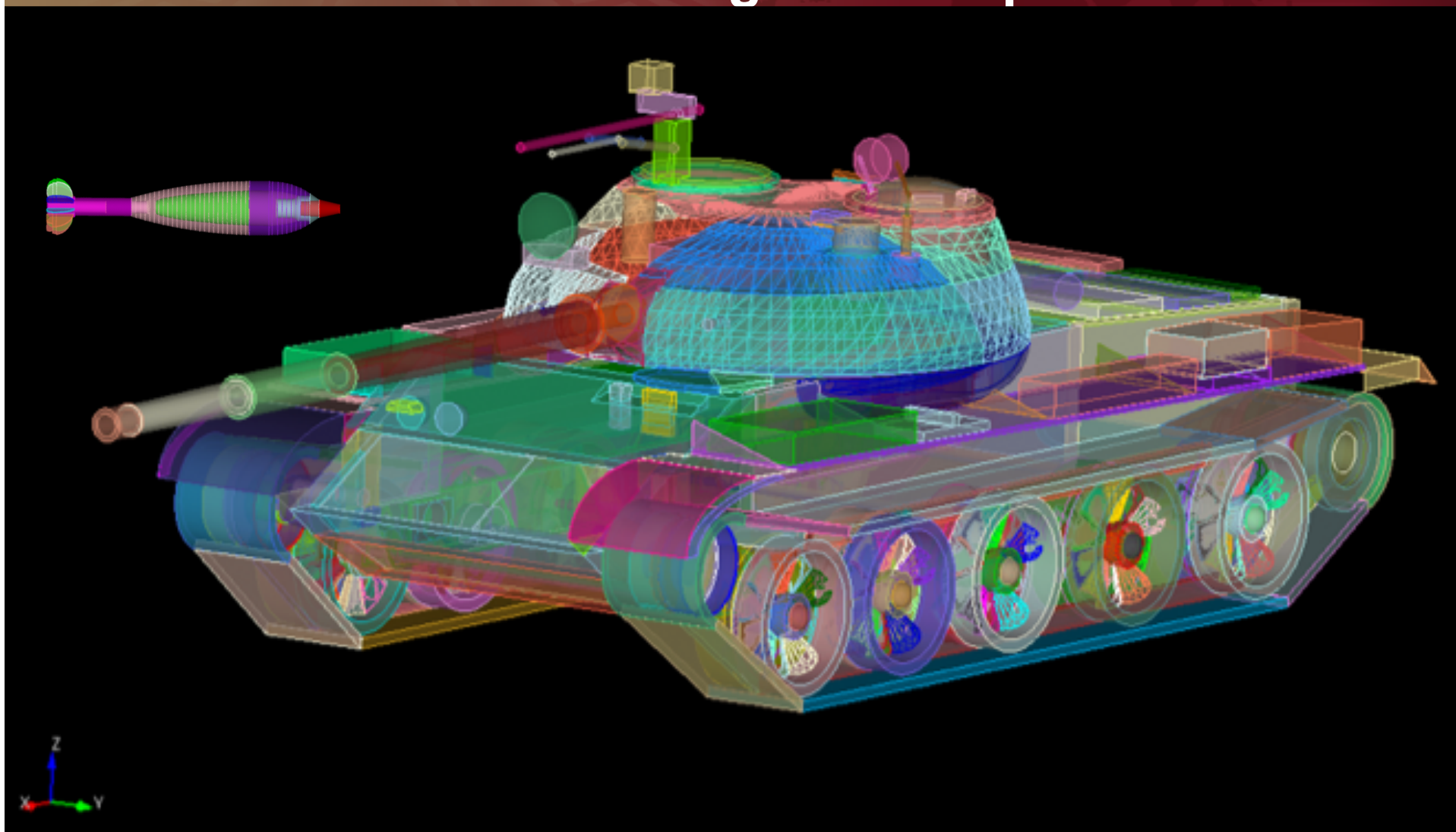
Truck with Blast Envelope	Glass Truck	Centers of Damage

- This methodology is integrated into MUVES-S2 for blast vulnerability predictions

Metaballs for Blast Volumes



Finite Element Analysis of BRL-CAD Target Descriptions



*Converted from BRL-CAD CSG format to a finite element mesh via g-sat and
CUBIT*

TECHNOLOGY DRIVEN. WARFIGHTER FOCUSED.



Main Goals



*BRL-CAD Tools & Techniques
for Visualization*

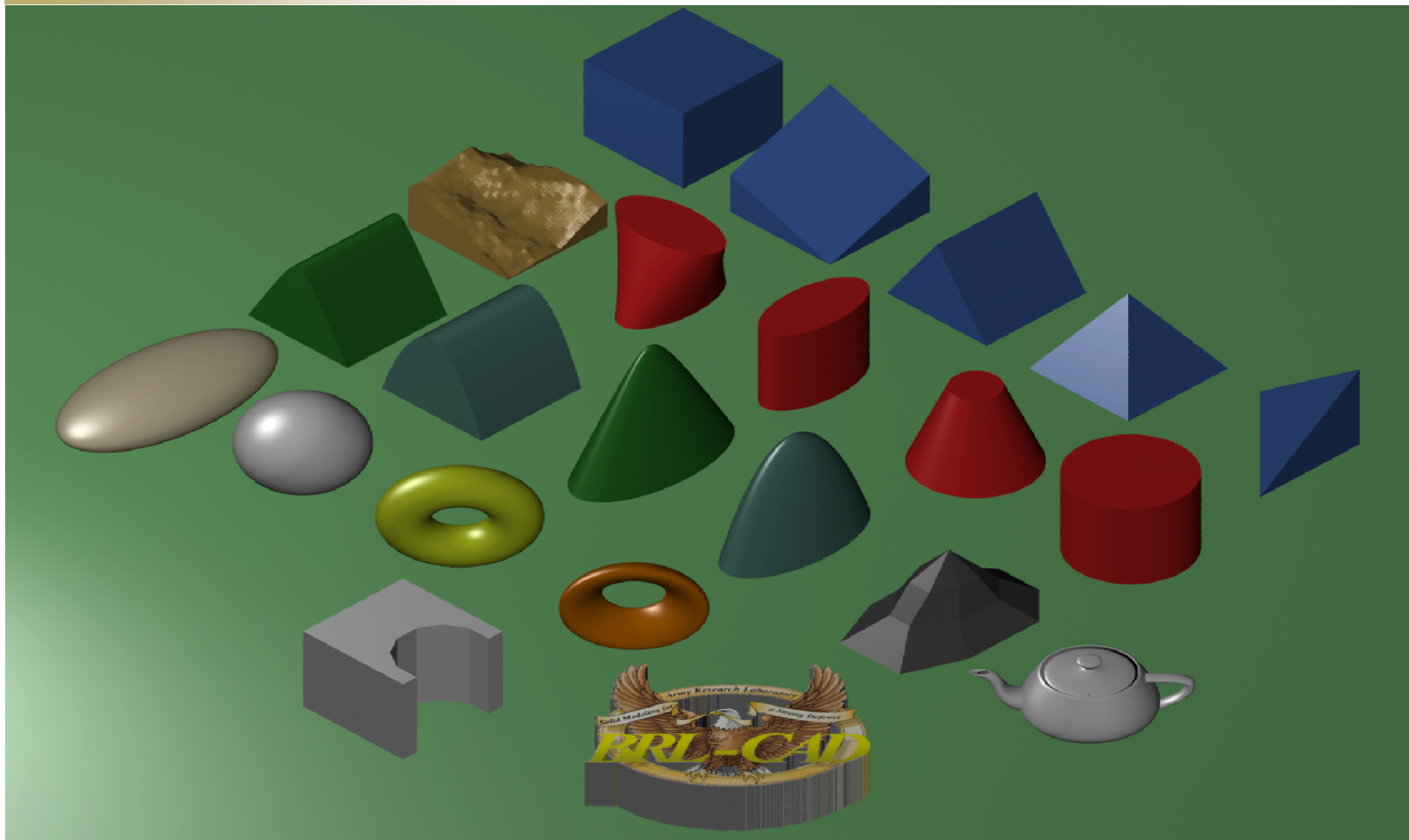
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***Boundary Representation & Conversion Support
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BRL-CAD Geometry Service & Parts Library



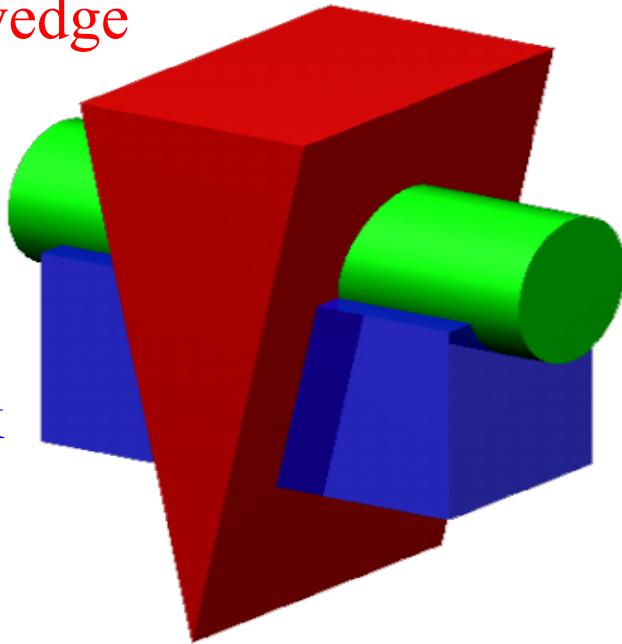
Some of BRL-CAD's Primitives



wedge

cylinder

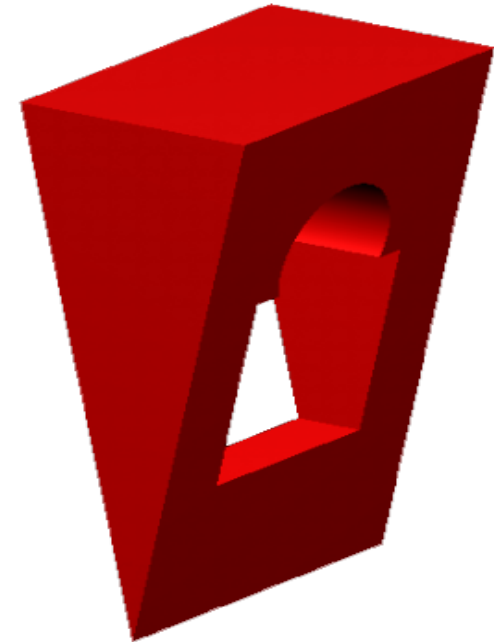
block



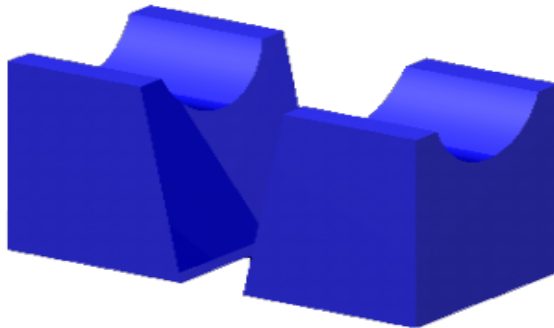
$(\text{wedge} \cap \text{block}) - \text{cylinder}$



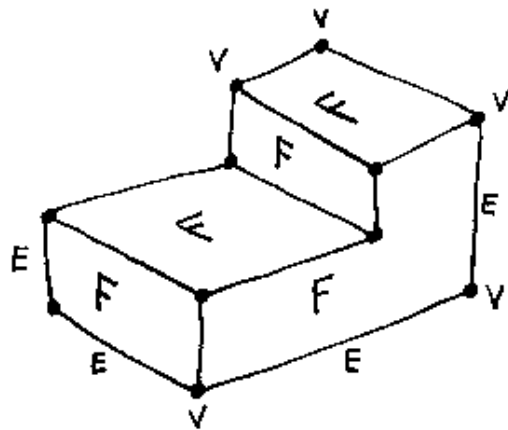
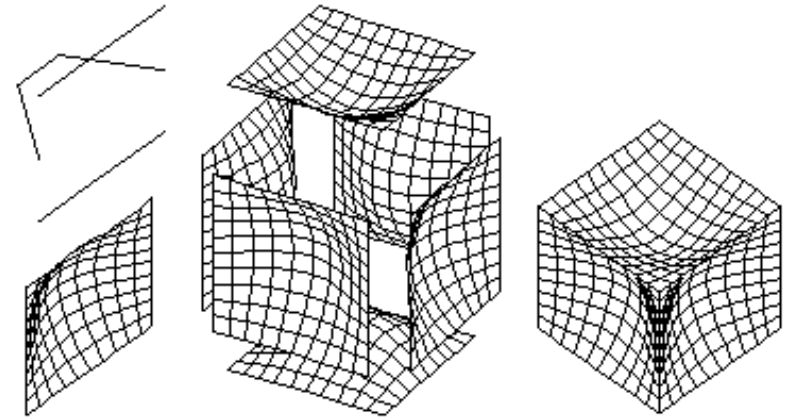
$\text{wedge} - \text{block} - \text{cylinder}$



$\text{block} - (\text{wedge} \cup \text{cylinder})$

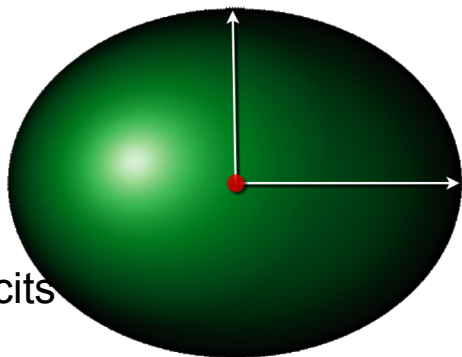


- Boundary representations are constructed from vertices, edges, and faces
 - NURBS surfaces also include trimming curves
- *Vertices* are joined to form *edges*
- *Edges* are joined to form *faces*
- Faces are connected to other faces on their edges in order to enclose space and represent a solid object (i.e., a “shell”)

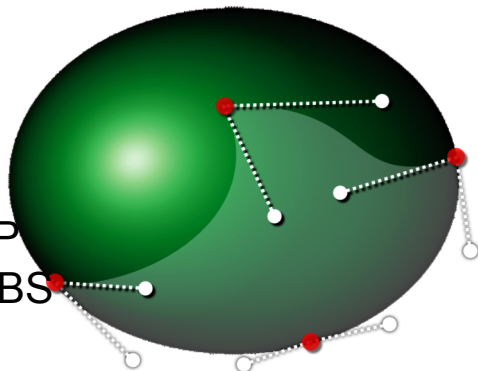


- » Where two faces are joined and share an edge, there is potential for **gaps** due to floating point precision
- » Extra care must be taken to ensure that a solidity constraint is preserved in order to obtain consistent and accurate results

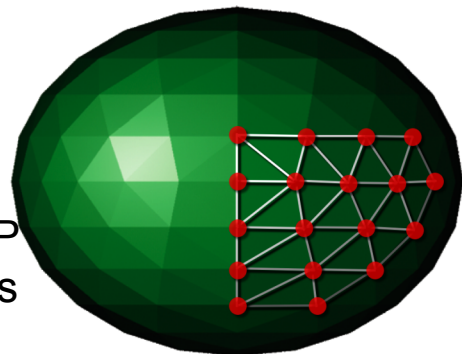
CSG
implicits



BREP
NURBS



BREP
facets



Geometric Definition

4 values

- Radius
- Position

Applications of Use

- Implicit primitives with constructive solid geometry (CSG) provide a representation format that is very compact and numerically robust (no cracks)

— Solidity constraint is guaranteed making it well-suited for solid modeling and engineering analysis purposes

200 values

- Surface
- Patches
- Knot
- Values
- Weights

- Spline surface boundary representations are prevalent in commercial CAD systems for their modeling flexibility

— More recently they are also the subject of real-time ray tracing computer graphics research

1000 values or more (configurable)

- Individual
- Polygons
- Vertices
- Normal values

- Polygonal boundary models are commonly used by display systems (e.g., OpenGL and DirectX) for interactive rendering and real-time visualization

— Many advancements have been made over the years on high-performance ray tracing of triangle models

TECHNOLOGY DRIVEN. WARFIGHTER FOCUSED.

Exponential Geometric Growth ↓	CSG <u>implicts</u>	2 MB
	BREP NURBS	20 MB
	BREP facets	200 MB



TECHNOLOGY DRIVEN. **WARFIGHTER FOCUSED.**



Example BREP Visualization



rviz.rvproj

State Vector

Type	State Vector
LOF	DAL_kills
LOF	ResidualPen
LOF	threatened
PK	crew_incapacitation
PK	critical component pks
Hit	critical component hits
Hit	critical component main hits
Hit	critical component spall hits
Killed	critical component kills

Results Hierarchy

Name	Value
16.0	
View	az:90 el:90 dir:(-0.000000 -0.000000 -1.000000)
View	az:0 el:0 dir:(-1.000000 0.000000 0.000000)
AimPoint	
Firing Point	[1] location:(7080.865383,400.000000,1200.000000)
Firing Point	[2] location:(14161.730766,895.372040,1314.000000)
Firing Point	[3] location:(14161.730766,769.165811,1011.000000)
Firing Point	[4] location:(14161.730766,717.475397,1242.000000)
Firing Point	[5] location:(14161.730766,208.843395,1551.000000)
Firing Point	[6] location:(14161.730766,925.040166,1453.000000)
Firing Point	[7] location:(14161.730766,261.182414,964.000000)
Firing Point	[8] location:(14161.730766,514.557101,732.000000)
Firing Point	[9] location:(14161.730766,575.664010,620.000000)
Firing Point	[10] location:(14161.730766,975.169767,1177.000000)
View	az:50 el:0 dir:(-0.500000 -0.866025 0.000000)

Property Value

Property	Value
Direction	(-1.0000,0.0000,0.0000)
Elevation	0.0000
Azimuth	0.0000

Comp. Name Is Shell? Show?

rt_brake		
rt_driv_sprok_		
rt_driv_sprok_		
rt_driv_sprok_		
rt_fndrv		
rt_frammis		
rt_frt_shkabs		
rt_frt_shkabs_		
rt_idlr_flange		
rt_idlr_hub		
rt_rack_tank		
rt_rear_shkabs		
rt_rear_shkabs		
rt_road_whl_1		
rt_road_whl_1		
rt_road_whl_1		
rt_road_whl_1		
rt_road_whl_1		
rt_road_whl_5		
rt_road_whl_5		
rt_road_whl_5		
rt_road_whl_5		
rt_road_whl_5		
rt_thingy		
rt_thingy_cove		
rt_track		
rt_track_teeth		
seven_air		
shell_hatch		
shell_hatch_ba		
slip_ring		
slip_ring_supp		
snorkel		
spare_track		
steering_brake		
storage_box		
throttle		
torsn_bar		
transfer		
transmission		
trav_mech		
tur_flr		
tur_ke_case		
tur_ring		
turret		
upr_glac		
vent_hatch		
ventilator		
ventilator_blov		
xmsn_hatch		
3-way_valve		

☒ Render Shell Components

Shell Opacity

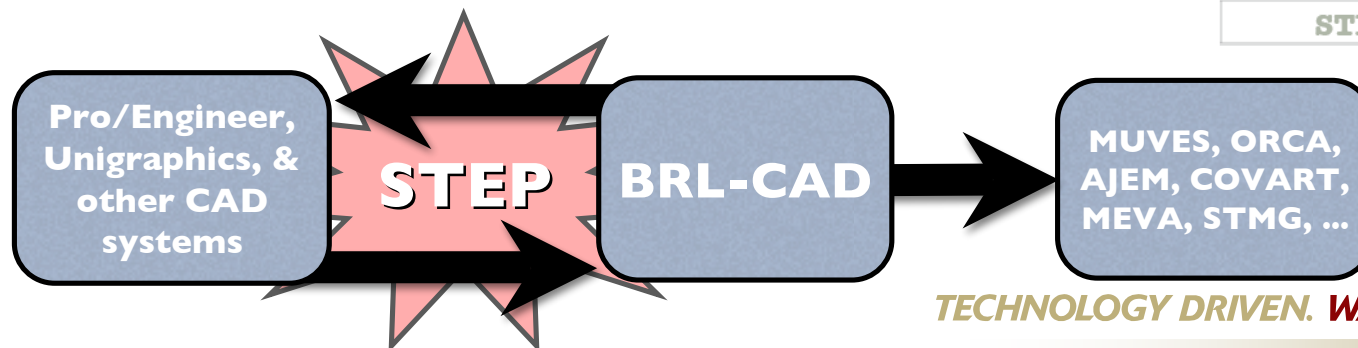
☐ Render Internal Components

Internal Opacity

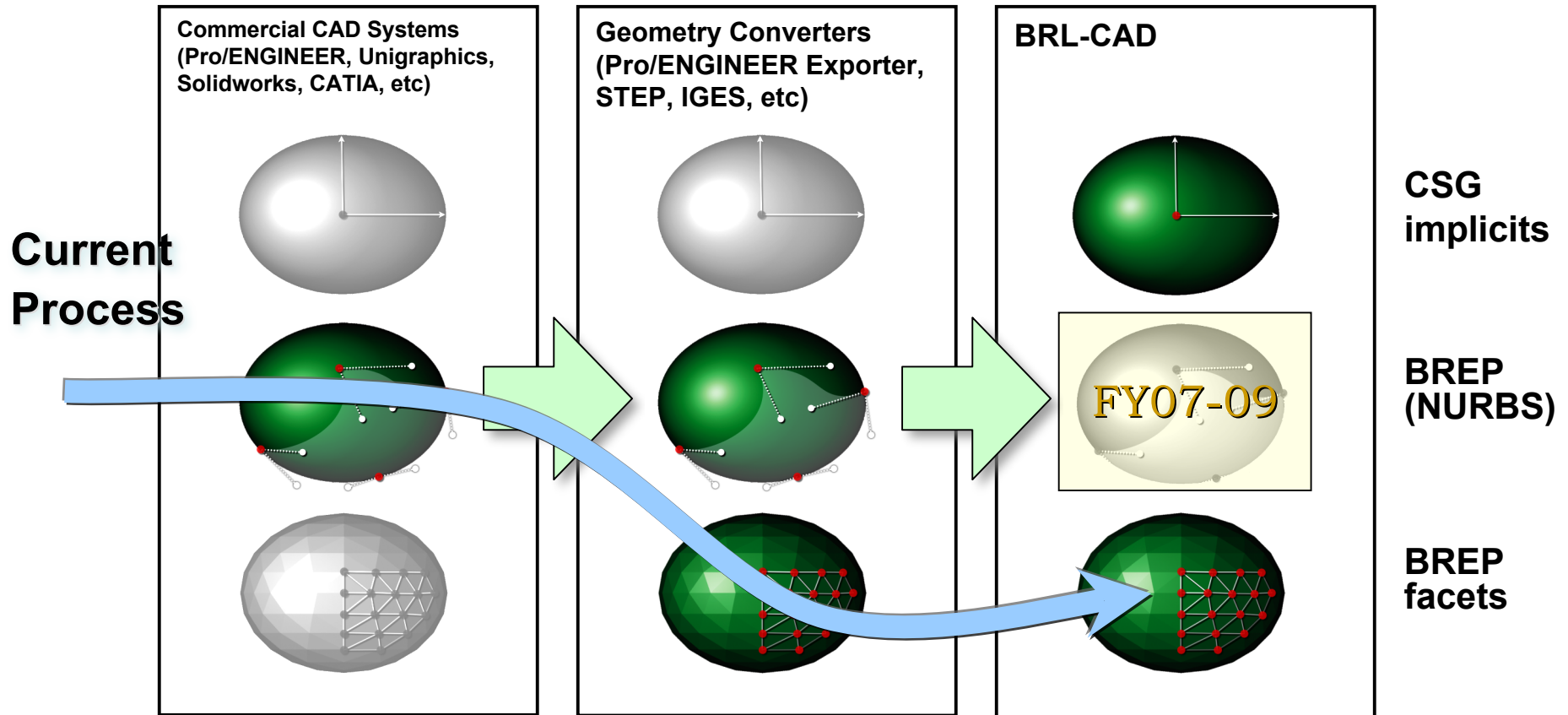
Prototype interactive target description visualization GUI made possible by using BRL-CAD geometry with a BREP facet representation

- Standard for the Exchange of Product Model Data (STEP) is an International Standards Organization (ISO) standard that
 - describes a vendor-neutral non-proprietary format for the exchange of geometry models
 - is supported by all major commercial CAD vendors
 - replaces the previous International Geometry Exchange Standard (IGES)
- Importing BREP geometry through a STEP converter
 - avoids changing the fundamental underlying geometric representation format
 - reduces introduction of new modeling errors
 - preserves existing geometric representation fidelity

Importers	Exporters
BRL-CAD ASCII	BRL-CAD ASCII
Comgeom	ADRT
CY	Lockheed ACAD
DXF	DXF
ENF	NFF
ASCII Euclid	ASCII Euclid
Fastgen	Wavefront OBJ
IGES	IGES
Jack	Jack
OFF	OFF
Nastran	VRML
Patch	X3D
PLY	
Pro/ENGINEER	
Rhino 3DM	
STL	STL
Tankill	Tankill
Unigraphics/NX	
Viewpoint	
STEP	STEP



TECHNOLOGY DRIVEN. WARFIGHTER FOCUSED.



- Geometry from most commercial CAD systems is imported by transforming the model from a spline surface-based BREP/NURBS representation to a BREP facet-based polygonal representation
- BREP/NURBS support in BRL-CAD allows geometry import without changing the underlying representation
 - Preserving the representation is crucial for ensuring robust, consistent, and correct analytic results
 - **Data representation changes introduce errors and greatly increase conversion time**



Main Goals



*BRL-CAD Tools & Techniques
for Visualization*

*BRL-CAD Tools & Techniques
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*Boundary Representation & Conversion Support
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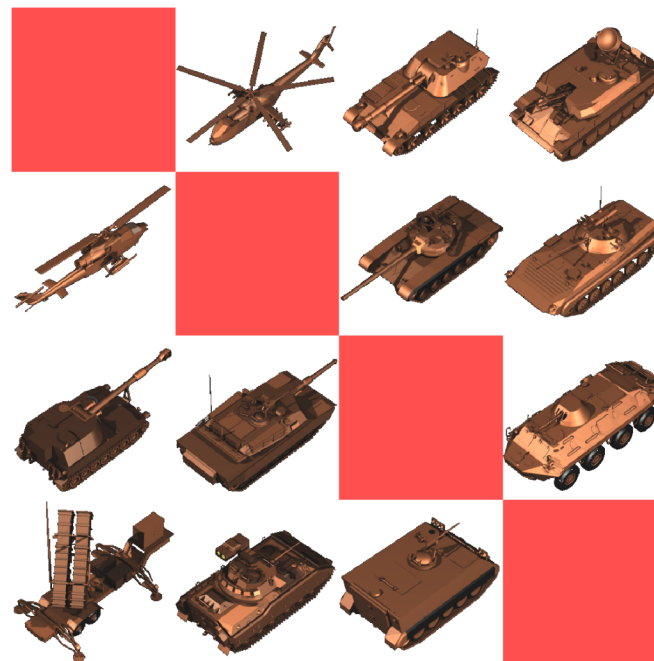
BRL-CAD Geometry Service & Parts Library



BRL-CAD Geometry Service

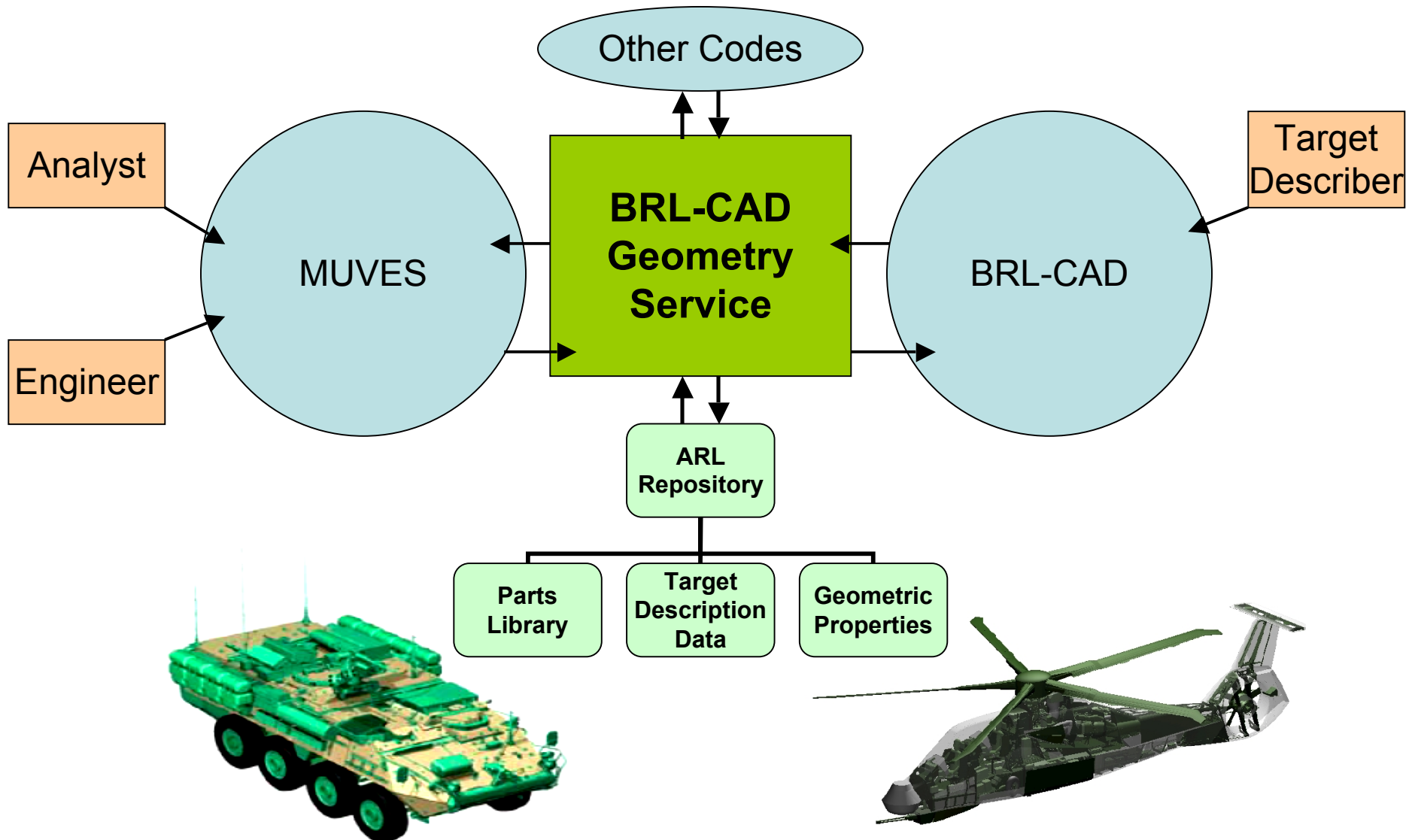


The *BRL-CAD Geometry Service* is a networked service interface for software application codes (e.g., *MUVES*, *ORCA*, and *BRL-CAD*) to access revision-controlled target description data and their geometric properties in a unified geometry parts library

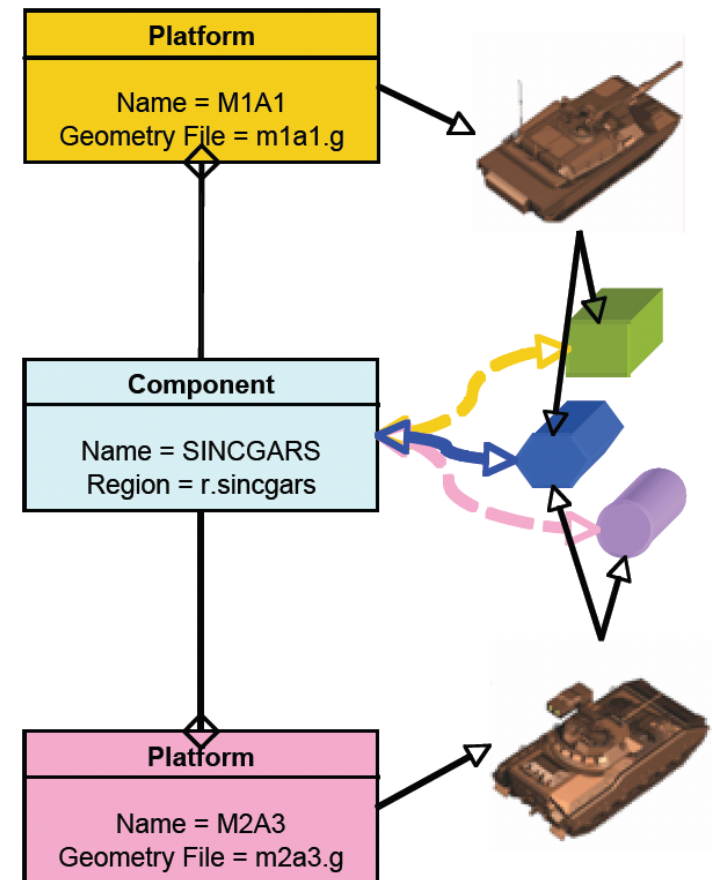


The BRL-CAD Geometry Service provides cross-application notification of changes to geometry and allows concurrent collaboration

TECHNOLOGY DRIVEN. WARFIGHTER FOCUSED.



- Can be readily integrated with ARL software codes including BRL-CAD, MUVES, ORCA, S4, and other software codes as a network geometry service
- Leverages existing infrastructure in BRL-CAD in a backwards-compatible manner
- BRL-CAD Geometry Service provides:
 - **Geometry versioning** (multiple threats/targets)
 - **Direct association** of targets/threats with analysis data
 - **Dynamic geometry** (for calculating multiple-hits and articulation support)
 - Vehicle **articulation** and editing constraints
 - **Unified repository** of targets in one storage location (automatic target description library)
 - **Reuse** of identical target geometry parts (single instancing)
 - Improved/advanced analyst and modeler **collaboration** (users can work in parallel)



Questions? Comments? Thank you!

Christopher Sean Morrison

morrison@arl.army.mil

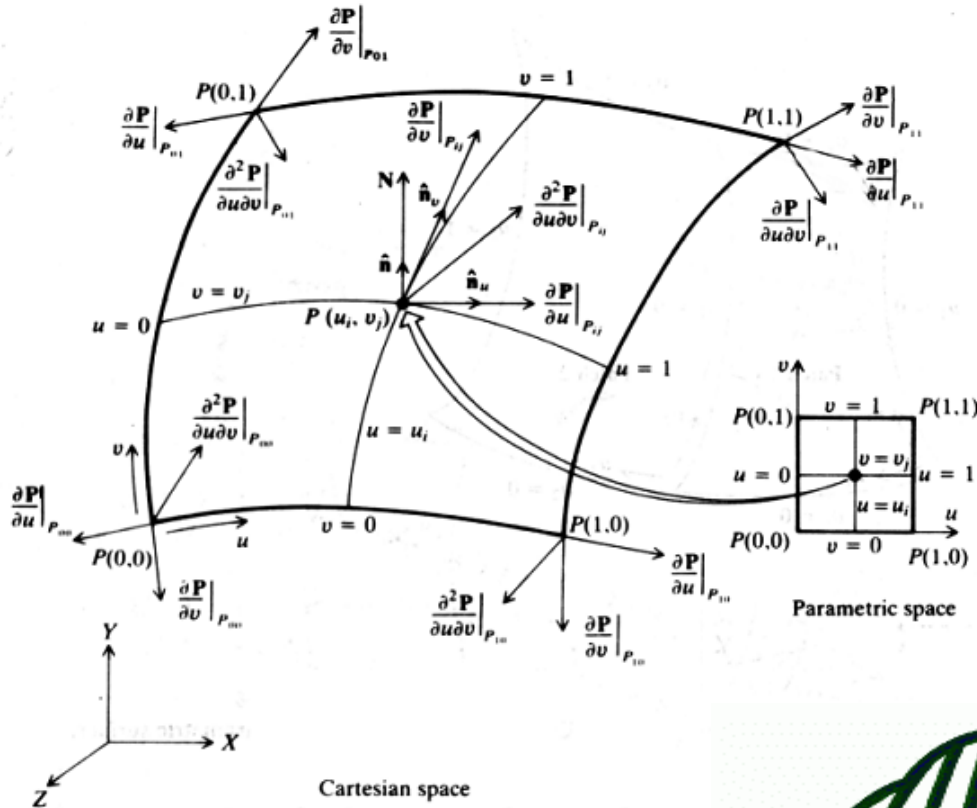
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Several of the images and videos contained within this presentation were created with the support and efforts of many individuals. The following deserve special recognition and thanks:

Mike Muuss
Lee Butler
Erik Greenwald
Ron Bowers
Jason Owens
Edwin Davisson
Mike Gillich
Cliff Yapp
Justin Shumaker
Geometric Solutions, Inc.

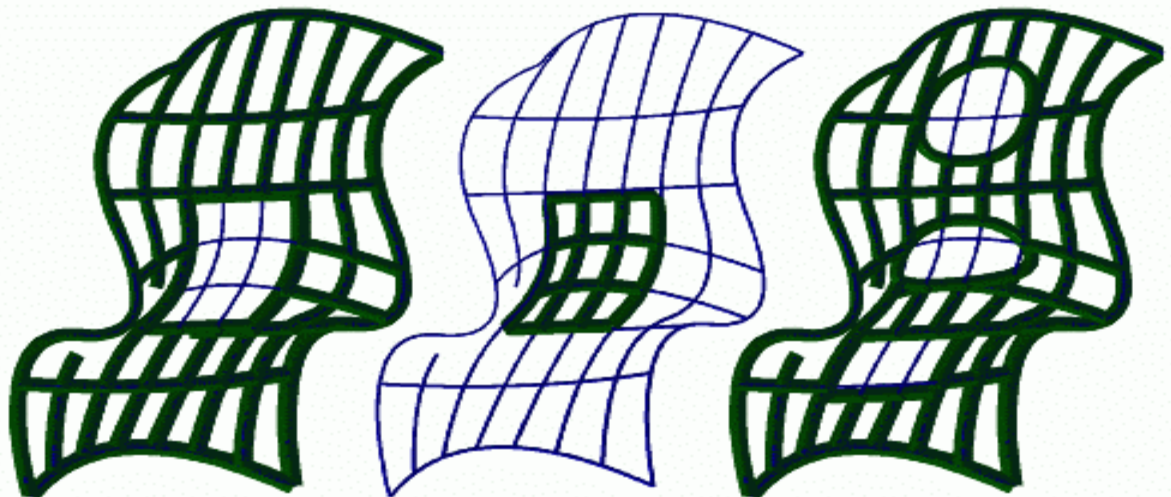


Additional Information about BRL-CAD

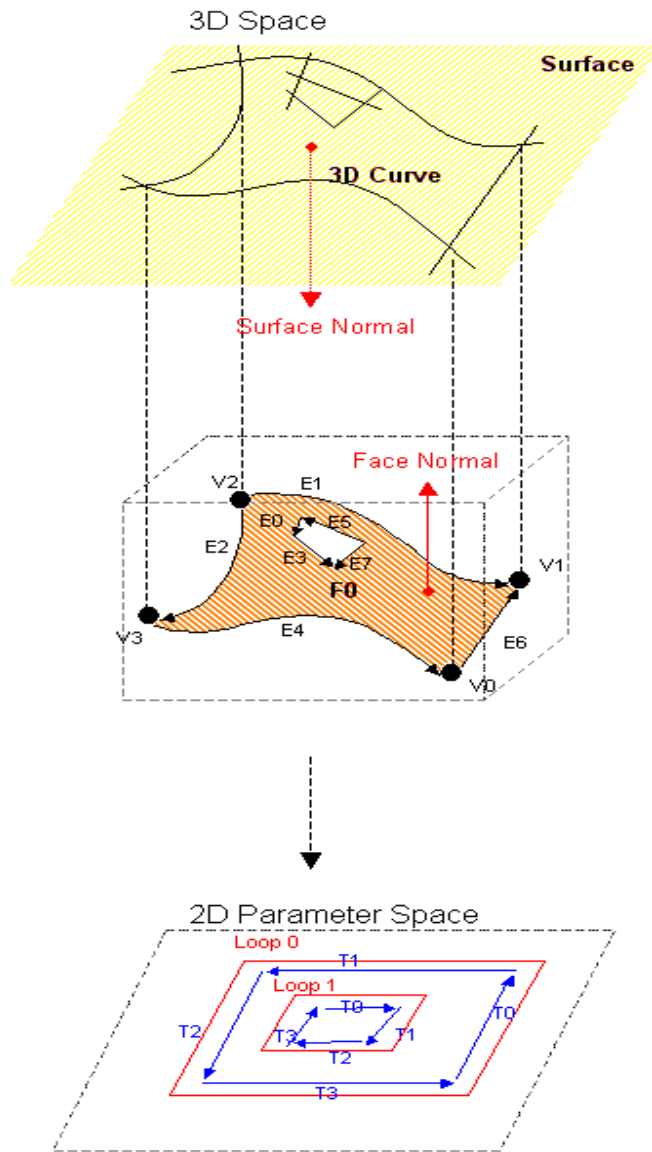


Shown on the left is a single spline surface showing how a point may be mapped from the surface's uv parametric space to a 3D Cartesian coordinate space.

Shown on the right are three identical surfaces, each with a different set of trimming curves



Boundary Representation (B-rep) in the context of OpenNURBS

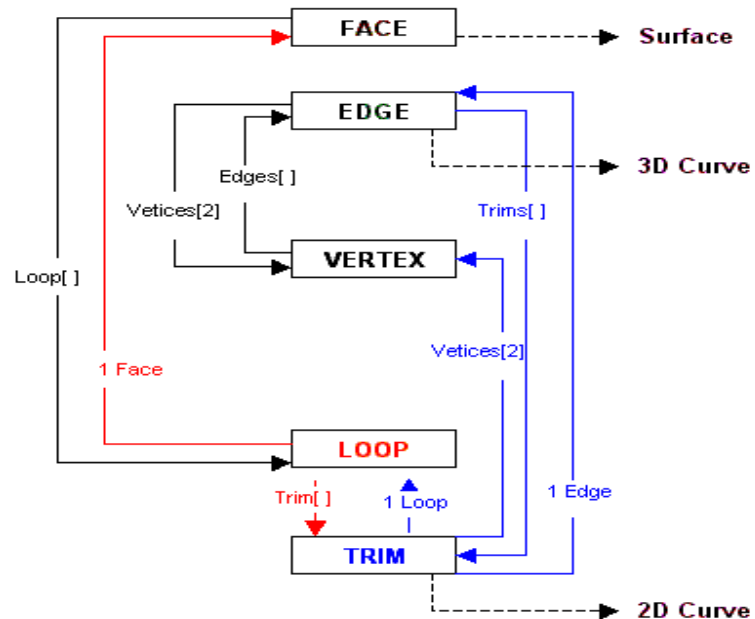
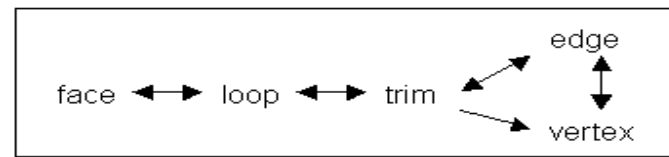


Boundary representation (B-rep) is used to unambiguously represent objects in terms of their boundary surfaces

```

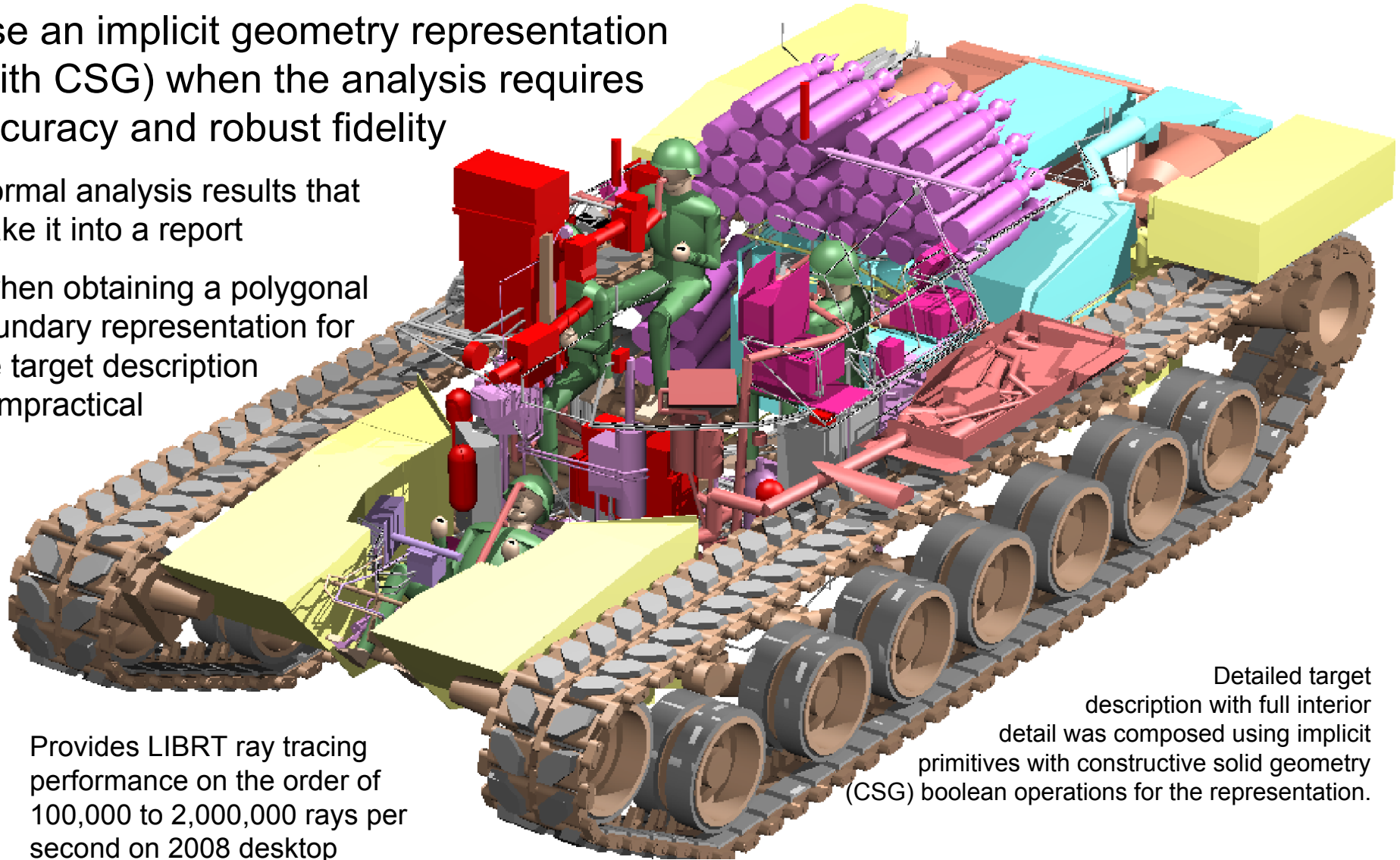
OH_Brep
//geometry
OH_CurveArray m_C2;
// Pointers to parameter space trimming curves
// (used by trims).
OH_CurveArray m_C3;
// Pointers to 3d curves (used by edges).
OH_SurfaceArray m_S;
// Pointers to parametric surfaces
// (used by faces)

// topology
OH_BrepVertexArray m_V; // vertices
OH_BrepEdgeArray m_E; // edges
OH_BrepTrimArray m_T; // trims
OH_BrepLoopArray m_L; // loops
OH_BrepFaceArray m_F; // faces
    
```



Use an implicit geometry representation (with CSG) when the analysis requires accuracy and robust fidelity

- formal analysis results that make it into a report
- when obtaining a polygonal boundary representation for the target description is impractical



Provides LIBRT ray tracing performance on the order of 100,000 to 2,000,000 rays per second on 2008 desktop hardware

Detailed target description with full interior detail was composed using implicit primitives with constructive solid geometry (CSG) boolean operations for the representation.

TECHNOLOGY DRIVEN. WARFIGHTER FOCUSED.



Example BREP facets model



Use a polygonal boundary representation (e.g., triangles) for visualization purposes

- detailed global illumination rendering
- high-performance interactive ray tracing

Provides ADRT ray tracing performance on the order of 250,000 to 10,000,000 rays per second on 2008 desktop hardware

Provides:

- Fast and interactive shotline queries
- Input assistance when preparing for detailed MUVES analyses
- Foundations for advanced modeling and graphical user interface design

Stryker ICV model was obtained directly from the manufacturer.

Model was converted to a polygonal representation for visualization purposes.



Stryker ICV w/ Slat Armor

146,542,892 Triangles

Rendered with ADRT/RISE

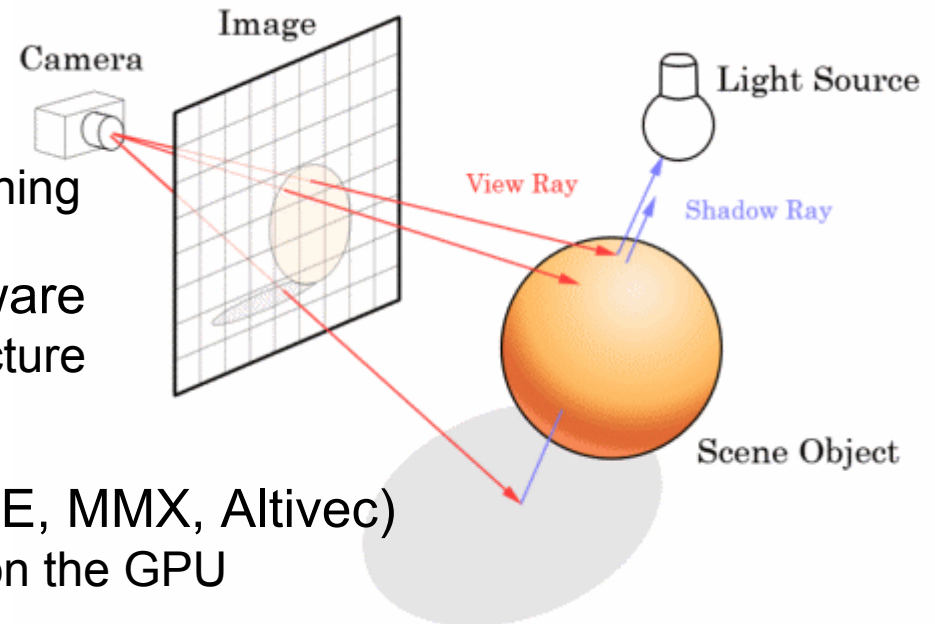
8 Trillion Rays

Recent conferences, publications, and presentations

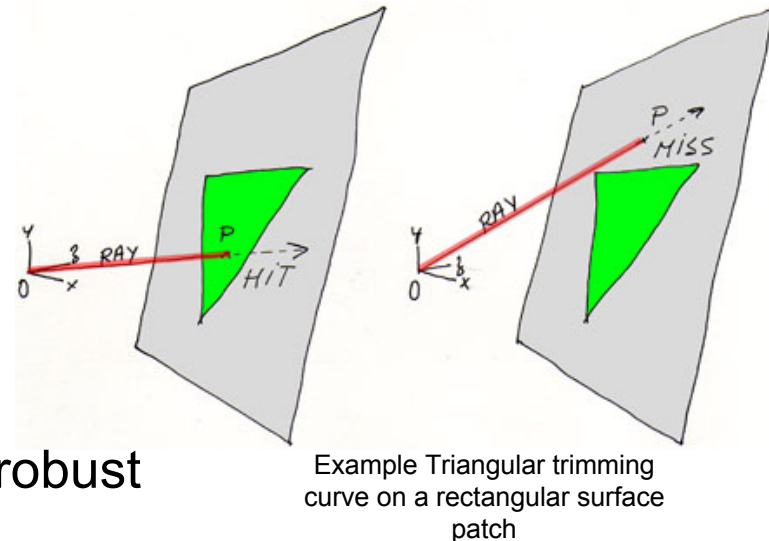
BRL-CAD has been actively developed and engaged in various communities for more than 20 years. Included below are some of the more recent interactions*:

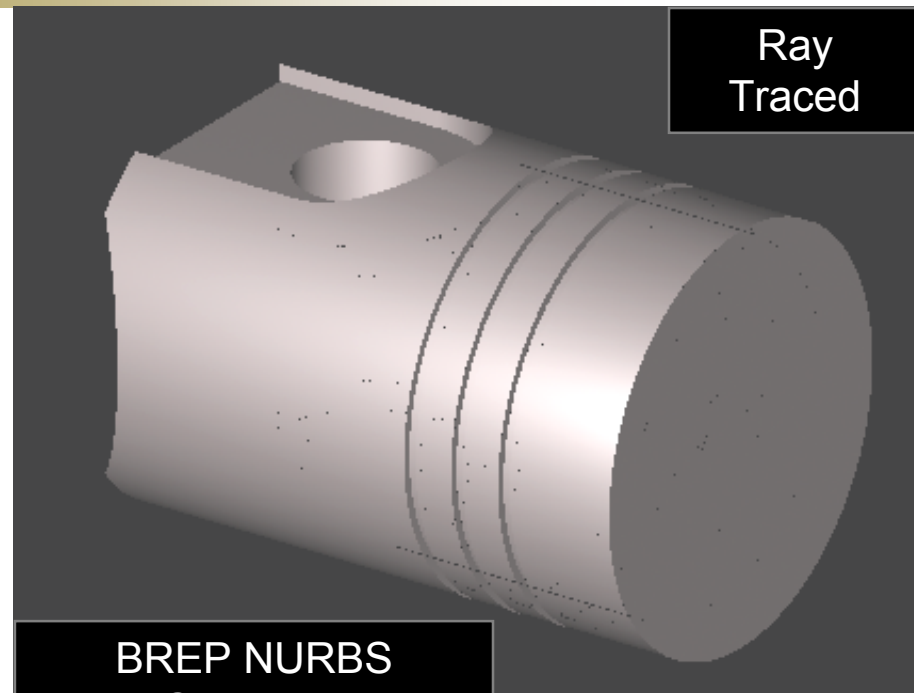
- Actively engaged in the computer graphics, visualization, high-performance computing, and solid modeling communities
 - IEEE Symposium on Shape Modeling (2006, 2008)
 - ACM Solid and Physical Modeling (2002, 2006, 2008)
 - ACM SIGGRAPH (every year, 1984-2007)
 - **BRL-CAD Birds of a Feather user group sessions (2005, 2006, 2008)**
 - **Published paper presentation (Butler 1997)**
 - IEEE Visualization (2002, 2006)
 - IEEE Symposium on Interactive Ray Tracing (2006, 2007)
 - **Published paper presentation (Butler 2007)**
 - IEEE/ACM International Conference for High Performance Computing, Networking, Storage, and Analysis (i.e. “IEEE/ACM Supercomputing” – 2002, 2004)
 - USENIX Tcl/Tk Conference (2001)
 - ... and more ...
 - Various technical presentations
 - **Open Source project management, Google Mentor Summit, Mountain View, CA (2007)**
 - **Introduction to BRL-CAD, Various Audiences & Locations (Morrison, 2006-2008)**
- presentations and publications given to public international audiences are in bold*
- **Open Source**
 - Active international user and developer community
 - Instrumental in working with VLAM counterparts
 - Made international slashdot.org announcement when released
 - More than three hundred mailing list subscriptions
 - Thousands of downloads per month, millions of on-line website visitors per year
 - Is recruitment avenue for new employees (one full-time, one part-time)
 - Extensive user documentation published to ARL and on-line audiences
 - **Vehicle Tire and Wheel Creation in BRL-CAD (Yapp, 2008)**
 - **Interactive Raytracing – the nirt Command (Yapp, 2008)**
 - **BRL-CAD Industry Diagram (Morrison, 2006)**
 - **MGED Quick Reference (Morrison, 2006)**
 - **BRL-CAD Overview Diagram (Morrison, 2006)**
 - **BRL-CAD Users Group Symposium (2002)**
 - International symposium hosted by the BRL-CAD Advanced Computer Systems Team
- TECHNOLOGY DRIVEN. WARFIGHTER FOCUSED.**

- Preserve cache coherency
 - Shoot rays in bundles
 - Use optimized space partitioning
- Run in parallel on SMP hardware
 - Utilize a distributed infrastructure for complex jobs
- Utilize SIMD vectorization(SSE, MMX, AltiVec)
 - Perform stream processing on the GPU
- BRL-CAD includes the Advanced Distributed Ray Tracer (ADRT) developed by Justin Shumaker for high-performance ray tracing of polygonal models
 - Includes the Interactive Shotline Selection Tool (ISST) for real-time visualization of target descriptions and predictive shotline selection
- The very first implementation of a “real-time” ray-tracer was credited at the 2005 SIGGRAPH computer graphics conference as BRL-CAD’s REMRT/RT tools developed by Mike Muuss in 1987

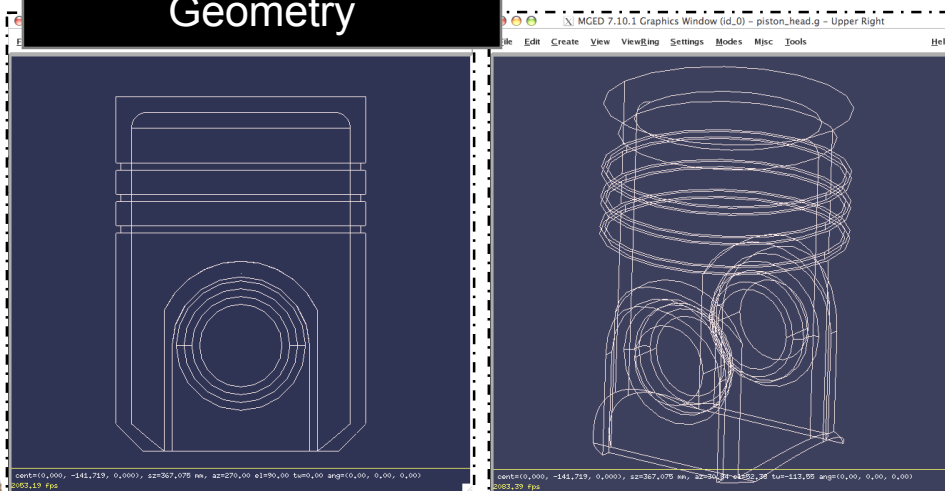


- Boundary representation (BREP) geometry involves stitching together 3D surfaces to hopefully form closed topological structures
- During ray-tracing, a ray can “slip through a crack” if the implementation is not sufficiently robust
- Floating point arithmetic increases the numerical instabilities substantially
- Fixed precision arithmetic provides much better stability but is several orders of magnitude slower to evaluate
- We are using the open source OpenNURBS library for BREP storage, but still have to implement routines for ray tracing and surface evaluation





BREP NURBS Geometry



Great progress made so far on BREP/NURBS support in BRL-CAD especially with OpenNURBS integration. However, we need to:

- ☐ Resolve tolerance and “acne” problems during ray tracing
- ☐ Optimize performance
- ☐ Develop a STEP geometry converter
- ☐ Implement surface-surface intersection routines